

1. Record Nr.	UNINA9910818043203321
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Titolo	Model-based visual tracking [[electronic resource]] : the OpenTL framework // Giorgio Panin
Pubbl/distr/stampa	Hoboken, N.J., : Wiley, c2011
ISBN	1-283-02573-6 9786613025739 1-118-00213-X 0-470-94392-0 0-470-94391-2
Edizione	[1st ed.]
Descrizione fisica	1 online resource (320 p.)
Disciplina	006.3/7
Soggetti	Automatic tracking - Mathematics Computer vision - Mathematical models Three-dimensional imaging - Mathematics
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	MODEL-BASED VISUALTRACKING: The OpenTL Framework; CONTENTS; PREFACE; CHAPTER 1: INTRODUCTION; CHAPTER 2: MODEL REPRESENTATION; CHAPTER 3: THE VISUAL MODALITY ABSTRACTION; CHAPTER 4: EXAMPLES OF VISUAL MODALITIES; CHAPTER 5: RECURSIVE STATE-SPACE ESTIMATION; CHAPTER 6: EXAMPLES OF TARGET DETECTORS; CHAPTER 7: BUILDING APPLICATIONS WITH OpenTL; APPENDIX A: POSE ESTIMATION; APPENDIX B: POSE REPRESENTATION; NOMENCLATURE; BIBLIOGRAPHY; INDEX; Color plates
Sommario/riassunto	This book has two main goals: to provide a unified and structured overview of this growing field, as well as to propose a corresponding software framework, the OpenTL library, developed by the author and his working group at TUM-Informatik. The main objective of this work is to show, how most real-world application scenarios can be naturally cast into a common description vocabulary, and therefore implemented and tested in a fully modular and scalable way, through the definition of a layered, object-oriented software architecture. The resulting architecture covers in a seamless way all processi

