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Nota di contenuto	The in-transit vigilant covering tour problem for routing unmanned ground vehicles / Huang Teng Tan and Raymond R. Hill -- Near-optimal assignment of UAVs to targets using a market-based approach / Elad Kivelevitch, Kelly Cohen and Manish Kumar -- Considering mine countermeasures exploratory operations conducted by autonomous underwater vehicles / Bao Nguyen, David Hopkin, and Handson Yip -- Optical search by UAVs : fauna detection case study / R. Prieto, E. Mendez, J.J. Vales, I. Pino, I.R. Carpintero, L. Granado, G. Montoya, F. Gimenez de Azcarate, F. Caceres and J.M. Moreira -- A flight time approximation model for unmanned aerial vehicles : estimating the effects of path variations and wind / Matthew J. Henchey, Rajan Batta, Mark Karwan and Agamemnon Crassidis -- Impacts of unmanned ground vehicles on combined arms team performance / Fred D. J. Bowden, Richard M. Dexter, Denis R. Shine, Andrew W. Coutts, Luke Finlay and Ben Pietsch -- Processing, exploitation and dissemination : when is aided/automated target recognition "good enough" for operational use? / Patrick Chisan Hew -- Analyzing a design continuum for automated military convoy operations / David M. Mahalak -- Experimental design for unmanned aerial systems analysis : bringing statistical rigor to UAS testing / Raymond R. Hill and Brian B. Stone --

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