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8.2.Ankle rehabilitation robot 8.3. Actuator force control; 8.4. Experimental results; 8.5.Concluding remarks; 8.6. Bibliography; Chapter 9. Performance Evaluation of a Probe Climber for Maintaining Wire Rope; 9.1. Introduction; 9.2.Optimize friction drive conditions using a prototype probe climber; 9.3. Impact of different surface friction materials for friction pulley made on elevation performance; 9.4.Damage detection test of elevator wire rope; 9.5.Damage detection through signal processing; 9.6.Integrity evaluation of wire rope through MFL strength
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Sommario/riassunto

Mechatronics represents a unifying interdisciplinary and intelligent engineering science paradigm that features an interdisciplinary knowledge area and interactions in terms of the ways of work and thinking, practical experiences, and theoretical knowledge. Mechatronics successfully fuses (but is not limited to) mechanics, electrical, electronics, informatics and intelligent systems, intelligent control systems and advanced modeling, intelligent and autonomous robotic systems, optics, smart materials, actuators and biomedical and biomechanics, energy and sustainable development, systems eng