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Nota di contenuto	Contents; Acknowledgments; Foreword; 1. Nonholonomically constrained motions; 1.1 Newton's equations; 1.2 Constraints; 1.3 Lagrange-d'Alembert equations; 1.4 Lagrange derivative in a trivialization; 1.5 Hamilton-d'Alembert equations; 1.6 Distributional Hamiltonian formulation; 1.6.1 The symplectic distribution (H,); 1.6.2 H and in a trivialization; 1.6.3 Distributional Hamiltonian vector field; 1.7 Almost Poisson brackets; 1.7.1 Hamilton's equations; 1.7.2 Nonholonomic Dirac brackets; 1.8 Momenta and momentum equation; 1.8.1 Momentum functions; 1.8.2 Momentum equations 1.8.3 Homogeneous functions 1.8.4 Momenta as coordinates; 1.9 Projection principle; 1.10 Accessible sets; 1.11 Constants of motion; 1.12 Notes; 2. Group actions and orbit spaces; 2.1 Group actions; 2.2 Orbit spaces; 2.3 Isotropy and orbit types; 2.3.1 Isotropy types; 2.3.2 Orbit types; 2.3.3 When the action is proper; 2.3.4 Stratification on by orbit types; 2.4 Smooth structure on an orbit space; 2.4.1 Differential structure; 2.4.2 The orbit space as a differential space; 2.5 Subcartesian spaces; 2.6 Stratification of the orbit space by orbit types;

2.6.1 Orbit types in an orbit space
 2.6.2 Stratification of an orbit space
 2.6.3 Minimality of S ; 2.7
 Derivations and vector fields on a differential space; 2.8 Vector fields
 on a stratified differential space; 2.9 Vector fields on an orbit space;
 2.10 Tangent objects to an orbit space; 2.10.1 Stratified tangent
 bundle; 2.10.2 Zariski tangent bundle; 2.10.3 Tangent cone; 2.10.4
 Tangent wedge; 2.11 Notes; 3. Symmetry and reductio; 3.1 Dynamical
 systems with symmetry; 3.1.1 Invariant vector fields; 3.1.2 Reduction of
 symmetry; 3.1.3 Reduction for a free and proper G -action; 3.1.4
 Reduction of a nonfree, proper G -action
 3.2 Nonholonomic singular reduction for a proper action
 3.3
 Nonholonomic reduction for a free and proper action; 3.4 Chaplygin
 systems; 3.5 Orbit types and reduction; 3.6 Conservation laws; 3.6.1
 Momentum map; 3.6.2 Gauge momenta; 3.7 Lifted actions and the
 momentum equation; 3.7.1 Lifted actions; 3.7.2 Momentum equation;
 3.8 Notes; 4. Reconstruction, relative equilibria and relative periodic
 orbits; 4.1 Reconstruction; 4.1.1 Reconstruction for proper free actions;
 4.1.2 Reconstruction for nonfree proper actions; 4.1.3 Application to
 nonholonomic systems; 4.2 Relative equilibria
 4.2.1 Basic properties
 4.2.2 Quasiperiodic relative equilibria; 4.2.3
 Runaway relative equilibria; 4.2.4 Relative equilibria when the action is
 not free; 4.2.5 Other relative equilibria in a G -orbit; 4.2.5.1 When the
 G -action is free; 4.2.5.2 When the G -action is not free; 4.2.6 Smooth
 families of quasiperiodic relative equilibria; 4.2.6.1 Elliptic, regular, and
 stably elliptic elements of \mathfrak{g} ; 4.2.6.2 When the G -action is free and
 proper; 4.2.6.3 When the G -action is proper but not free; 4.3 Relative
 periodic orbits; 4.3.1 Basic properties; 4.3.2 Quasiperiodic relative
 periodic orbits
 4.3.3 Runaway relative period orbits

Sommario/riassunto

This book gives a modern differential geometric treatment of linearly nonholonomically constrained systems. It discusses in detail what is meant by symmetry of such a system and gives a general theory of how to reduce such a symmetry using the concept of a differential space and the almost Poisson bracket structure of its algebra of smooth functions. The above theory is applied to the concrete example of Caratheodory's sleigh and the convex rolling rigid body. The qualitative behavior of the motion of the rolling disk is treated exhaustively and in detail. In particular, it classifies all mot
