Record Nr. UNINA9910808453903321 Micro, nanosystems, and systems on chips [[electronic resource]]: **Titolo** modeling, control, and estimation / / edited by Alina Voda Pubbl/distr/stampa London, : ISTE Hoboken, N.J., : Wiley, c2010 **ISBN** 1-118-55781-6 1-299-31845-2 1-118-62267-7 1-61344-555-5 Edizione [1st ed.] Descrizione fisica 1 online resource (330 p.) ISTE Collana VodaAlina Altri autori (Persone) Disciplina 621.381 Soggetti Microelectromechanical systems Systems on a chip Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Note generali Description based upon print version of record. Nota di bibliografia Includes bibliographical references and index. Nota di contenuto Cover: Title Page: Copyright Page: Table of Contents: Introduction: PART I. MINI AND MICROSYSTEMS; Chapter 1. Modeling and Control of Stick-slip Micropositioning Devices; 1.1. Introduction; 1.2. General description of stick-slip micropositioning devices; 1.2.1. Principle; 1.2.2. Experimental device; 1.3. Model of the sub-step mode; 1.3.1. Assumptions: 1.3.2. Microactuator equation: 1.3.3. The elastoplastic friction model: 1.3.4. The state equation: 1.3.5. The output equation: 1.3.6. Experimental and simulation curves; 1.4. PI control of the substep mode; 1.5. Modeling the coarse mode 1.5.1. The model1.5.2. Experimental results; 1.5.3. Remarks; 1.6. Voltage/frequency (U/f) proportional control of the coarse mode; 1.6.1. Principle scheme of the proposed controller; 1.6.2. Analysis; 1.6.3. Stability analysis: 1.6.4. Experiments: 1.7. Conclusion: 1.8. Bibliography; Chapter 2. Microbeam Dynamic Shaping by Closed-loop Electrostatic Actuation using Modal Control; 2.1. Introduction; 2.2. System description; 2.3. Modal analysis; 2.4. Mode-based control; 2.4.1. PID control; 2.4.2. FSF-LTR control; 2.5. Conclusion; 2.6.

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Sommario/riassunto

Micro and nanosystems represent a major scientific and technological challenge, with actual and potential applications in almost all fields of the human activity. The aim of the present book is to present how concepts from dynamical control systems (modeling, estimation, observation, identification, feedback control) can be adapted and applied to the development of original very small-scale systems and of their human interfaces. The application fields presented here come from micro and nanorobotics, biochips, near-field microscopy (AFM and STM) and nanosystems networks. Alina Voda has drawn