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flight"; "1.4.3 Data processing"; "1.4.4 Airborne laser scanning and cameras"; "1.4.5 Advantages and limitations of airborne laser scanning"; "1.5 Airborne lidar bathymetry"
"1.6 Terrestrial laser scanners""Acknowledgements"; "References";
"Chapter 2 Visualisation and Structuring"; "2.1 Visualisation"; "2.1.1 Conversion of point clouds to images"; "2.1.2 Point-based rendering"; "2.2 Data structures"; "2.2.1 Delaunay triangulation"; "2.2.2 Octrees"; "2.2.3 k-D tree"; "2.3 Point cloud segmentation"; "2.3.1 3D Hough transform"; "2.3.2 The random sample consensus algorithm"; "2.3.3 Surface growing"; "2.3.4 Scan line segmentation"; "2.4 Data compression"; "References"; "Chapter 3 Registration and Calibration"
"3.1 Geometric models""3.1.1 Rotations"; "3.1.2 The geometry of terrestrial laser scanning"; "3.1.3 The geometry of airborne laser scanning"; "3.2 Systematic error sources and models"; "3.2.1 Systematic errors and models of terrestrial laser scanning"; "3.2.2 Errors and models for airborne laser scanning"; "3.3 Registration"; "3.3.1 Registration of terrestrial laser scanning data"; "3.3.2 Registration of airborne laser scanning data"; "3.4 System calibration"; "3.4.1 Calibration of terrestrial laser scanners"; "3.4.2 Calibration of airborne laser scanners"
"Summary""References"; "Chapter 4 Extraction of Digital Terrain Models"; "4.1 Filtering of point clouds"; "4.1.1 Morphological filtering"; "4.1.2 Progressive densification"; "4.1.3 Surface-based filtering"; "4.1.4 Segment-based filtering"; "4.1.5 Filter comparison"; "4.1.6 Potential of full-waveform information for advanced filtering"; "4.2 Structure line determination"; "4.3 Digital terrain model generation"; "4.3.1 Digital terrain model determination from terrestrial laser scanning data"; "4.3.2 Digital terrain model quality"
"4.3.3 Digital terrain model data reduction"
