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Altri autori (Persone)	LeVu Tuan Hieu CastanieFrancis
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Sommario/riassunto

This title focuses on two significant problems in the field of automatic control, in particular state estimation and robust Model Predictive Control under input and state constraints, bounded disturbances and measurement noises. The authors build upon previous results concerning zonotopic set-membership state estimation and output feedback tube-based Model Predictive Control. Various existing zonotopic set-membership estimation methods are investigated and their advantages and drawbacks are discussed, making this book suitable both for researchers working in automatic control and industrial pa
