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| Nota di contenuto       | Cover; TItle Page; Copyright; Contents; Foreword; Preface; Introduction;<br>Suggested Bibliography; List of main symbols and definitions; Chapter<br>1 Analytical Dynamics of Discrete Systems; Definitions; 1.1 Principle of<br>virtual work for a particle; 1.1.1 Nonconstrained particle; 1.1.2<br>Constrained particle; 1.2 Extension to a system of particles; 1.2.1<br>Virtual work principle for N particles; 1.2.2 The kinematic constraints;<br>1.2.3 Concept of generalized displacements; 1.3 Hamilton's principle<br>for conservative systems and Lagrange equations<br>1.3.1 Structure of kinetic energy and classification of inertia forces1.3.2<br>Energy conservation in a system with scleronomic constraints; 1.3.3<br>Classification of generalized forces; 1.4 Lagrange equations in the<br>general case; 1.5 Lagrange equations for impulsive loading; 1.5.1<br>Impulsive loading of a mass particle; 1.5.2 Impulsive loading for a<br>system of particles; 1.6 Dynamics of constrained systems; 1.7<br>Exercises; 1.7.1 Solved exercises; 1.7.2 Selected exercises; References;<br>Chapter 2 Undamped Vibrations of n-Degree-of-Freedom Systems;<br>Definitions<br>2.1 Linear vibrations about an equilibrium configuration2.1.1<br>Vibrations about a stable equilibrium position; 2.1.2 Free vibrations |

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|                    | about an equilibrium configuration corresponding to steady motion;<br>2.1.3 Vibrations about a neutrally stable equilibrium position; 2.2<br>Normal modes of vibration; 2.2.1 Systems with a stable equilibrium<br>configuration; 2.2.2 Systems with a neutrally stable equilibrium<br>position; 2.3 Orthogonality of vibration eigenmodes; 2.3.1<br>Orthogonality of elastic modes with distinct frequencies; 2.3.2<br>Degeneracy theorem and generalized orthogonality relationships<br>2.3.3 Orthogonality relationships including rigid-body modes2.4<br>Vector and matrix spectral expansions using eigenmodes; 2.5 Free<br>vibrations induced by nonzero initial conditions; 2.5.1 Systems with a<br>stable equilibrium position; 2.5.2 Systems with neutrally stable<br>equilibrium position; 2.6 Response to applied forces: forced harmonic<br>response; 2.6.1 Harmonic response, impedance and admittance<br>matrices; 2.6.2 Mode superposition and spectral expansion of the<br>admittance matrix; 2.6.3 Statically exact expansion of the admittance<br>matrix; 2.6.4 Pseudo-resonance and resonance<br>2.6.5 Normal excitation modes2.7 Response to applied forces:<br>response in the time domain; 2.7.1 Mode superposition and normal<br>equations; 2.7.3 Step response and time integration of the normal<br>equations; 2.7.4 Direct integration of the transient response; 2.8 Modal<br>approximations of dynamic responses; 2.8.1 Response truncation and<br>mode displacement method; 2.8.2 Mode acceleration method; 2.8.3<br>Mode acceleration and model reduction on selected coordinates; 2.9<br>Response to support motion<br>2.9.1 Motion imposed to a subset of degrees of freedom |
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| Sommario/riassunto | "Mechanical Vibrations: Theory and Application to Structural Dynamics,<br>Third Edition is a comprehensively updated and reorganized new<br>edition of the popular textbook. It presents the theory of vibrations in<br>the context of structural analysis and covers applications in mechanical<br>and aerospace engineering, This new edition now includes the<br>fundamentals of signal processing and identification technique, and<br>develops the concepts of dynamic reduction and substructuring. A more<br>detailed discussion of the concept of eigensolution sensitivity to<br>physical parameters is included and the fundamental cases of wave<br>propagation in solids are considered. It also includes a chapter on the<br>finite element method for one-dimensional structures. This new edition<br>contains coherent and uniform notation and now includes solved<br>exercises at the end of each chapter"  |