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| Nota di contenuto       | Front Cover; Modeling and Precision Control of Systems With Hysteresis; Copyright; Contents; Preface; Acknowledgments; Chapter 1: Introduction; 1.1 Motivation; 1.2 Literature Review; 1.3 Book Objectives; 1.4 Book Overview; References; Chapter 2: Fundamentals of Systems with Hysteresis; 2.1 Introduction; 2.2 Smart Systems with Hysteresis; 2.3 Mechanical and Capacitor Dynamics; 2.4 Static Hysteresis; 2.4.1 Preisach Hysteresis; 2.4.2 Preisach Plane; 2.4.3 Preisach Hysteresis Properties; Wiping-out Property; Rate-Independence Property; Congruence Property<br>2.5 Behavior Comparison of Preisach Hysteresis and Phase Delay under Sinusoidal Inputs<br>2.6 Closed-Loop Response of Smart Systems with Hysteresis; 2.7 Dynamic Hysteresis; 2.8 Composite Representation of Dynamic Hysteresis; 2.9 Modeling Suggestions for Systems with Hysteresis ; 2.10 Conclusions; References; Chapter 3: Hysteresis Modeling in Smart Actuators; 3.1 Introduction; 3.2 Simplified Composite Representation of Smart Actuators; 3.2.1 Static Preisach Hysteresis; 3.2.2 Simplified Composite Representation; 3.2.3 Closed-loop Control Property<br>3.2.4 Simplified Identification Approach for Composite Hysteresis<br>Hysteresis Measurable; Hysteresis Unmeasurable; 3.2.5 Simplified Control of Linear Dynamics with Input Static Preisach |

Hysteresis; 3.2.6 Persistent-Excitation Problem; 3.3 Creep Effect; 3.3.1 Linear Creep Model; 3.3.2 Coupled Hysteresis and Creep Effects; 3.4 Mechanical Vibration and the RC Effect in Piezoelectric Actuators ; 3.5 Dynamics and Effects of Smart Actuators at Different Frequencies; References; Chapter 4: Comprehensive Modeling of Multifield Hysteretic Dynamics; 4.1 Introduction  
4.2 Description of a Piezoelectric Smart System  
4.2.1 Typical Structure of a Piezoelectric Smart System; 4.2.2 Working Principle of a Capacitive Displacement Sensor; 4.3 Multifield Modeling of the Hysteretic Dynamics; 4.3.1 Multifield Modeling of the Hysteretic Dynamics; 4.4 Identification Strategy Design; 4.4.1 Pre-execution of the Creep, Electrical, and Vibration Dynamics; 4.4.2 Identification of the Creep, Electrical, and Vibration Dynamics; 4.4.3 Identification of the Preisach Hysteresis; 4.5 Experimental Studies of the Proposed Modeling and Identification; 4.5.1 Experimental Setup  
4.5.2 Identification Result for the Creep, Electrical, and Vibration Dynamics  
4.5.3 Identification Result for the Preisach Hysteresis; 4.5.4 Discussion; 4.6 Complete Modeling of Hysteretic Dynamics in Piezoelectric Smart Systems with High Stiffness; 4.7 Conclusion; References; Chapter 5: Control Approaches for Systems with Hysteresis; 5.1 Introduction; 5.2 PID Control Tuning; 5.2.1 Ziegler-Nichols Tuning Control; 5.2.2 Ziegler-Nichols Tuning of Systems with Hysteresis; 5.2.3 Integral Control; 5.3 Inversion-Based Feedforward Control; 5.3.1 Preisach Hysteresis-Based Feedforward Control  
5.3.2 Composite Hysteresis-Based Feedforward Control

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## Sommario/riassunto

Modelling and Precision Control of Systems with Hysteresis covers the piezoelectric and other smart materials that are increasingly employed as actuators in precision engineering, from scanning probe microscopes (SPMs) in life science and nano-manufacturing, to precision active optics in astronomy, including space laser communication, space imaging cameras, and the micro-electro-mechanical systems (MEMS). As smart materials are known for having hysteretic dynamics, it is necessary to overcome issues with a broadband range of frequencies. This book offers both the mathematical tools for modeling the systems and applications, including complete case studies and source code for the experiments to help both academics and researchers in the industry to achieve precision in the control of Smart Actuator systems.

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