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| Autore | Zhao, Xuegong |
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| Titolo | Intelligent Robotics and Applications : 9th International Conference, ICIRA 2016, Tokyo, Japan, August 22-24, 2016, Proceedings, Part I / / edited by Naoyuki Kubota, Kazuo Kiguchi, Honghai Liu, Takenori Obo |
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| Collana | Lecture Notes in Artificial Intelligence, , 2945-9141 ; ; 9834 |
| Disciplina | 629.892 |
| Soggetti | Artificial intelligence
Image processing - Digital techniques
Computer vision
Control engineering
Robotics
Automation
Computers and civilization
Application software
User interfaces (Computer systems)
Human-computer interaction
Artificial Intelligence
Computer Imaging, Vision, Pattern Recognition and Graphics
Control, Robotics, Automation
Computers and Society
Computer and Information Systems Applications |

Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Robot Control -- Robot Mechanism, Robot Vision and Sensing -- Planning, Localization, and Mapping -- Interactive Intelligence -- Cognitive Robotics -- Bio-Inspired Robotics -- Smart Material Based Systems -- Mechatronics Systems for Nondestructive Testing -- Social Robotics -- Human Support Robotics -- Assistive Robotics -- Intelligent Space -- Sensing and Monitoring in Environment and Agricultural Sciences -- Human Data Analysis -- Robot Hand.
Sommario/riassunto	This two volume set LNAI 9834 and 9835 constitutes the refereed proceedings of the 9th International Conference on Intelligent Robotics and Applications, ICIRA 2016, held in Tokyo, Japan, in August 2016. The 114 papers presented were carefully reviewed and selected from 148 submissions. The papers are organized in topical sections such as Robot Control; Robot Mechanism, Robot Vision and Sensing; Planning, Localization, and Mapping; Interactive Intelligence; Cognitive Robotics; Bio-Inspired Robotics; Smart Material Based Systems; Mechatronics Systems for Nondestructive Testing; Social Robotics; Human Support Robotics; Assistive Robotics; Intelligent Space; Sensing and Monitoring in Environment and Agricultural Sciences; Human Data Analysis; Robot Hand.