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Nota di contenuto	<p>""Chapter 4. <math>L_{\sub(n)}</math> and <math>I_{\sub(n,i)}</math> as Semi-Invariants of the First Kind""</p> <p>""Chapter 5. <math>V_{\sub(n)}</math> and <math>J_{\sub(n,i)}</math> as Semi-Invariants of the Second Kind""</p> <p>""Chapter 6. The Coefficients of Transformed Equations""</p> <p>""6.1. Alternative formulas for <math>c^{\sub(i)}(l?)</math> in (1.5)""</p> <p>""6.2. The coefficients of a composite transformation""</p> <p>""6.3. Several examples""</p> <p>""6.4. Proof of an old observation""</p> <p>""6.5. Conditions for transformed equations""</p> <p>""6.6. Formulas for later reference""</p> <p>""Chapter 7. Formulas That Involve <math>L_{\sub(n)}(z)</math> or <math>I_{\sub(n,n)}(z)</math>""</p> <p>""7.1. The coefficients of (6.8) when <math>d_{\sub(1)}(l?) a?_i d_{\sub(2)}(l?) a?_i 0</math>""</p> <p>""7.2. Derivatives for the coefficients of (6.8) when <math>d_{\sub(1)}(l?) a?_i d_{\sub(2)}(l?) a?_i 0</math>""</p> <p>""7.3. Identities for the coefficients of (6.8) when <math>d_{\sub(1)}(l?) a?_i d_{\sub(2)}(l?) a?_i 0</math>""</p> <p>""Chapter 8. Formulas That Involve <math>V_{\sub(n)}(z)</math> or <math>J_{\sub(n,n)}(z)</math>""</p> <p>""8.1. The coefficients of (6.8) when <math>d_{\sub(1)}(l?) a?_i d_{\sub(2)}(l?) a?_i 0</math>""</p> <p>""8.2. Derivatives for the coefficients of (6.8) when <math>d_{\sub(1)}(l?) a?_i d_{\sub(2)}(l?) a?_i 0</math>""</p> <p>""8.3. Identities for the coefficients of (6.8) when <math>d_{\sub(1)}(l?) a?_i d_{\sub(2)}(l?) a?_i 0</math>""</p> <p>""Chapter 9. Verification of <math>I_{\sub(n,n)} a?_i J_{\sub(n,n)}</math> and Various Observations""</p> <p>""9.1. Proof for the first part of the Main Theorem in Chapter 1""</p> <p>""9.2. Global sets""</p> <p>""9.3. A fourth type of invariant: an absolute invariant""</p> <p>""9.4. Laguerre-Forsyth canonical</p>

forms"; "Chapter 10. The Local Constructions of Earlier Research";  
"10.1. Standard techniques"; "10.2. An improved computational  
procedure"; "10.3. Hindrances to earlier research"  
"Chapter 11. Relations for  $G_{(i)}$ ,  $H_{(i)}$ , and  $L_{(i)}$  That Yield  
Equivalent Formulas for Basic Relative Invariants"

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