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control problem ( Case d = 3)"; "4.2. Optimal feedback dynamics: the feedback semigroup and its generator on W"; "4.3. Feedback synthesis via the Riccati operator"; "4.4. Identification of the Riccati operator R in ( 4.1.8) with the operator R<sub>[1]</sub> in ( 4.3.1)"

"4.5. A Riccatia€?type algebraic equation satisfied by the operator R on the domain D(A<sup>2</sup>)[Sub(R)], Where A<sub>[R]</sub> is the feedback generator""Chapter 5. Theorem 2.3(i): Wellposedness of the Naviera€?Stokes equations with Riccatia€?based boundary feedback control. Case d = 3 "; "Chapter 6. Theorem 2.3(ii): Local uniform stability of the Naviera€?Stokes equations with Riccatia€?based boundary feedback control"; "Chapter 7. A PDEa€?interpretation of the abstract results in Sections 5 and 6"; "Appendix A. Technical Material Complementing Section 3.1"

"B.3. Completion of the proof of Theorem 2.5 and Theorem 2.6 for the Na€?S model (1.1), d = 2"

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