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partitioning method; REFERENCES

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2. The algorithm  
3. Convergence of the Algorithm; 4. Rate of Convergence of the Algorithm; 5. Discussion; REFERENCES; Chapter 8. Convergent Step-Sizes for Gradient-Like Feasible Direction Algorithms for Constrained Optimization; ABSTRACT; 1. Introduction; 2. Gradient-like feasible direction algorithms; 3. General stepsize criteria; 4. Step sizes based on minimization; 5. Step sizes based on a range function; 6. Step sizes based on a search procedure; 7. Example of directions: variable metric gradient projections; REFERENCES; Chapter 9. On the Implementation of Conceptual Algorithms; ABSTRACT  
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2. Conceptual algorithms; 3. Adaptive Procedures for Implementation; 4. Open Loop Procedures for Implementation; 5. Conclusion; REFERENCES; Chapter 10. Some Convex Programs Whose Duals Are Linearly Constrained; ABSTRACT; 1. Introduction; 2. Dual problems; 3. The nature of problem (D1); 4. Examples; 5. Relationships between (P), (D) and (D1); REFERENCES; Chapter 11. Sufficiency Conditions and a Duality Theory for Mathematical Programming Problems in Arbitrary Linear Spaces; ABSTRACT; 1. Introduction; 2. Mathematical preliminaries and problem statement  
3. Necessary conditions and sufficient conditions

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Sommario/riassunto

Nonlinear Programming

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