Record Nr. UNINA9910786030603321 Artificial intelligence research and development [[electronic resource]]: **Titolo** proceedings of the 15th International Conference of the Catalan Association for Artificial Intelligence / / edited by David Riano, Eva Onaindia, and Miguel Cazorla Pubbl/distr/stampa Amsterdam; ; Washington, DC, : IOS Press, 2012 **ISBN** 1-283-92040-9 1-61499-139-1 Descrizione fisica 1 online resource (260 p.) Collana Frontiers in artificial intelligence and applications;; v. 248 Altri autori (Persone) RianoDavid OnaindiaEva CazorlaMiguel Disciplina 573.8 Soggetti Artificial intelligence Computer science Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Note generali Description based upon print version of record. Nota di bibliografia Includes bibliographical references and indexes. Title Page: Preface: Conference Organization: Contents: Invited Talks: Nota di contenuto Some Real-World Applications of Soft Artificial Intelligence: Scientogram Mining, Assembly Line Balancing, and Forensic Identification; Challenges of Automation and Safety in Field Robotics; KDD, DM and Machine Learning; Data Mining and Query Answer Techniques Applied to a Bio-Nutritional Trials Focused Expert System; The Use of the Traffic Lights Panel as a Goodness-of-Clustering Indicator: An Application to Financial Assets Using Gabriel Graphs in Borderline-SMOTE to Deal with Severe Two-Class Imbalance Problems on Neural NetworksActive Learning of Actions Based on Support Vector Machines; Towards the Formalization of Re-Identification for Some Data Masking Methods; Natural Language Processing and Recommenders: Towards Object Descriptions in Natural Language from Qualitative Models; Semantically-Enhanced Recommenders; Computer Vision; Supervised Texture Classification

Using Optimization Techniques; Modelling Facial Expressions Dynamics with Gaussian Process Regression; Survey on 2D and 3D Human Pose

## Recovery

A Study of Registration Techniques for 6DoF SLAMRobotics; Object Detection Methods for Robot Grasping: Experimental Assessment and Tuning; The Role of i-Walker in Post-Stroke Training; Using a RGB-D Camera for 6DoF SLAM; Learning Topological SLAM Using Visual Information; AI for Optimization Problems; Exploring Genetic Algorithms and Simulated Annealing for Immobile Location-Allocation Problem; Analysis and Generation of Pseudo-Industrial MaxSAT Instances; A SAT-Based Approach to MinSAT; Multicast Session Protection Planner - Tool to Plan and Deploy Protection Infrastructure: A SPEA Approach

Al Applications to Real WorldA Case-Based Hybrid System for Injection Molding Sensorization; First Studies on Self-Preserving Digital Objects; Intelligent Building Energy Management Through Holistic Knowledge Based Approach; Quantitative and Qualitative Approaches for Stock Movement Prediction; Subject Index; Author Index