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Sadd Martin H (Martin Howard)
Elasticity [[electronic resource] ] : theory, applications, and numerics / / Martin H. Sadd
Amsterdam ; ; Oxford, : Elsevier Butterworth Heinemann, c2005
1-281-00834-6 9786611008345
0-08-047747-X
[1st edition]
1 online resource (474 p.)
531.382
Elasticity
Mathematical physics
Inglese
Materiale a stampa
Monografia
Description based upon print version of record.
Includes bibliographical references and index.
Cover; Front matter; Half Title Page; Title Page; Copyright; Preface; Contents; About the Author; Part I: Foundations and Elementary Applications; 1. Mathematical Preliminaries; 1.1 Scalar, Vector, Matrix, and Tensor Definitions; 1.2 Index Notation; 1.3 Kronecker Delta and Alternating Symbol; 1.4 Coordinate Transformations; 1.5 Cartesian Tensors; 1.6 Principal Values and Directions for Symmetric Second- Order Tensors; 1.7 Vector, Matrix, and Tensor Algebra; 1.8 Calculus of Cartesian Tensors; 1.9 Orthogonal Curvilinear Coordinates; References; Exercises; 2. Deformation: Displacements and Strains 2.1 General Deformations 2.2 Geometric Construction of Small Deformation Theory; 2.3 Strain Transformation; 2.4 Principal Strains; 2.5 Spherical and Deviatoric Strains; 2.6 Strain Compatibility; 2.7 Curvilinear Cylindrical and Spherical Coordinates; References; Exercises; 3. Stress and Equilibrium; 3.1 Body and Surface Forces; 3.2 Traction Vector and Stress Tensor; 3.3 Stress Transformation; 3.4 Principal Stresses; 3.5 Spherical and Deviatoric Stresses; 3.6 Equilibrium Equations; 3.7 Relations in Curvilinear Cylindrical and Spherical Coordinates; References; Exercises 4. Material Behavior-Linear Elastic Solids 4.1 Material Characterization;

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	Exercises; 5. Formulation and Solution Strategies; 5.1 Review of Field Equations; 5.2 Boundary Conditions and Fundamental Problem Classifications; 5.3 Stress Formulation; 5.4 Displacement Formulation; 5.5 Principle of Superposition; 5.6 Saint-Venant's Principle; 5.7 General Solution Strategies; References; Exercises; 6. Strain Energy and Related Principles; 6.1 Strain Energy 6.2 Uniqueness of the Elasticity Boundary-Value Problem 6.3 Bounds on the Elastic Constants; 6.4 Related Integral Theorems; 6.5 Principle of Virtual Work; 6.6 Principles of Minimum Potential and Complementary Energy; 6.7 Rayleigh-Ritz Method; References; Exercises; 7. Two- Dimensional Formulation; 7.1 Plane Strain; 7.2 Plane Stress; 7.3 Generalized Plane Stress; 7.4 Antiplane Strain; 7.5 Airy Stress Function; 7.6 Polar Coordinate Formulation; References; Exercises; 8. Two- Dimensional Problem Solution; 8.1 Cartesian Coordinate Solutions Using Polynomials 8.2 Cartesian Coordinates; 8.4 Polar Coordinate Solutions; References; Exercises; 9. Extension, Torsion, and Flexure of Elastic Cylinders; 9.1 General Formulation; 9.2 Extension Formulation; 9.3 Torsion Formulation; 9.4 Torsion Solutions Derived from Boundary Equation; 9.5 Torsion Solutions Using Fourier Methods; 9.6 Torsion of Cylinders With Hollow Sections; 9.7 Torsion of Circular Shafts of Variable Diameter; 9.8 Flexure Formulation; 9.9 Flexure Problems Without Twist; References; Exercises Part II: Advanced Applications
Sommario/riassunto	Although there are several books in print dealing with elasticity, many focus on specialized topics such as mathematical foundations, anisotropic materials, two-dimensional problems, thermoelasticity, non-linear theory, etc. As such they are not appropriate candidates for a general textbook. This book provides a concise and organized presentation and development of general theory of elasticity. Complemented by an online Solutions Manual and companion website, and including MatLab codes and coding, this text is an excellent book teaching guide Contains exercises for student engagement