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5.9 Spinning satellite 5.10 De-spinning of satellites; 5.11 Stability of aircraft; 5.12 Stability of a road vehicle; Chapter 6. Impact and One-Dimensional Wave Propagation; 6.1 Introduction; 6.2 The one-dimensional wave; 6.3 Longitudinal waves in an elastic prismatic bar; 6.4 Reflection and transmission at a boundary; 6.5 Momentum and energy in a pulse; 6.6 Impact of two bars; 6.7 Constant force applied to a long bar; 6.8 The effect of local deformation on pulse shape; 6.9 Prediction of pulse shape during impact of two bars; 6.10 Impact of a rigid mass on an elastic bar; 6.11 Dispersive waves
6.12 Waves in a uniform beam 6.13 Waves in periodic structures; 6.14 Waves in a helical spring; Chapter 7. Waves in a Three-Dimensional Elastic Solid; 7.1 Introduction; 7.2 Strain; 7.3 Stress; 7.4 Elastic constants; 7.5 Equations of motion; 7.6 Wave equation for an elastic solid; 7.7 Plane strain; 7.8 Reflection at a plane surface; 7.9 Surface waves (Rayleigh waves); 7.10 Conclusion; Chapter 8. Robot Arm Dynamics; 8.1 Introduction; 8.2 Typical arrangements; 8.3 Kinematics of robot arms; 8.4 Kinetics of a robot arm; Chapter 9. Relativity; 9.1 Introduction
9.2 The foundations of the special theory of relativity

Sommario/riassunto

'Advanced Engineering Dynamics' bridges the gap between elementary dynamics and advanced specialist applications in engineering. It begins with a reappraisal of Newtonian principles before expanding into analytical dynamics typified by the methods of Lagrange and by Hamilton's Principle and rigid body dynamics. Four distinct vehicle types (satellites, rockets, aircraft and cars) are examined highlighting different aspects of dynamics in each case. Emphasis is placed on impact and one dimensional wave propagation before extending the study into three dimensions. Robotics is then looked a
