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Altri autori (Persone)	LegnaniGiovanni Fassilrene
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Nota di contenuto	Preface / Irene Fassi and Giovanni Legnanivii -- Robot in industrial applications : state of the art and current trends / L. Tirloni, I. Fassi and G. Legnani -- A partially-decoupled 4-dof general 3SPS/PS parallel manipulator / Chin-Hsing Kuo and Jian S. Dai -- Manipulators workspace analysis as based on a numerical approach : theory and applications / Gianni Castelli and Erika Ottaviano -- On the mobility of 3-dof parallel manipulators via screw theory / E. Rodriguez-Leal, J. S. Dai and G. R. Pennock -- An application of screw algebra to the jerk analysis of a class of six degrees of freedom three legged parallel manipulators / Jaime Gallardo Alvarado, Karla A. Camarillo-Gomez and Ramon Rodriguez-Castro -- Dynamics and system identification of parallel robots / Gloria J. Wiens and Young-Hoon Oh -- Fractional-order controllers for robot manipulator / Hadi Delavariand Danial Mohammadi Senejohnny -- Visual control of robotic manipulators : fundamentals / Paulo J .S. Goncalves and Pedro M. B. Torres -- Flexible applications of robotic manipulators based on visual-force control and cooperation with humans / J. A. Corrales, G. J. Garcia, F. Torres, F. A. Candelas, J. Pomares and P. Gil -- Robotics in rehabilitation - part I : requirements and control issues / Matteo Malosio, Nicola Pedrocchi, Federico Vicentini, Lorenzo Molinari Tosatti, Marco Caimmi and Franco Molteni -- Robotics in rehabilitation - part II : design of devices and

mechanisms / Matteo Malosio, Nicola Pedrocchi, Federico Vicentini,  
Lorenzo Molinari Tosatti, Marco Caimmi and Franco Molteni -- An  
overview on robotic micromanipulation / D. Sinan Haliyo and Stephane  
Regnier.

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