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Autore	Minetor Randi
Titolo	Cursed in New York : stories of the damned in the Empire State // Randi Minetor
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ISBN	1-4930-1377-7
Descrizione fisica	1 online resource (225 p.)
Collana	Cursed
Disciplina	398.209747
Soggetti	Evil eye - New York (State) Blessing and cursing - New York (State) Revenge - New York (State) New York (State) Social life and customs Anecdotes New York (State) Biography Anecdotes
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di contenuto	Contents; Preface; Introduction; 1: Ancient, Unsportsmanlike Souls; 2: The Indian Princess of Lake Ronkonkoma; 3: The Truth About Shakespeare's Scottish Play; 4: The Curse of Mamie O'Rourke; 5: The Lost Souls of Seneca County; 6: The Black Dog of the Great Lakes; 7: The Rangers, the Stanley Cup, and the Curse of 1940; 8: The Death of a President and the Teams that Fail to Thrive; 9: Gustav Mahler and the Curse of the Ninth Symphony; 10: Devil's Hole: The Cave of the Evil Spirit; 11: The Hex Murder at the Stone Arch Bridge; 12: Murder in the Well: Hamilton, Burr, and the Quaker Curse 13: The Power of a Maleficent Gem 14: The Curse of the Black Orlov 15: The Widow's Curse on Hyde Hall 16: The Castle in the Catskills 17: Bringing Malocchio to America 18: The Scandalous Case of the Witch of Easthampton 19: "Wicked and Detestable Arts" in Seatallcott 20: The Knicks, the Red Bulls, and the Worst Luck in Sports 21: The Farmer, the Beggar, and the Peach Orchard 22: The Legend of Thirteen Curves 23: Phantom Ships on the Hudson 24: The Cursed Ghost of Alice Van der Veer 25: Politics and Painted Poultry Sources; Acknowledgments; Index; About the Author

Sommario/riassunto

A collection of riveting stories about preternatural revenge. Some stories will be regionally well known. Others are nearly forgotten. All are cursed.

2. Record Nr.**Autore**

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Titolo

Fault-Tolerant Cooperative Control of Unmanned Aerial Vehicles / / by Ziquan Yu, Youmin Zhang, Bin Jiang, Chun-Yi Su

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Descrizione fisica

1 online resource (226 pages)

Altri autori (Persone)

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Disciplina

629.8

Soggetti

Automatic control

Robotics

Automation

Aerospace engineering

Astronautics

Control, Robotics, Automation

Aerospace Technology and Astronautics

Control and Systems Theory

Lingua di pubblicazione

Inglese

Formato

Materiale a stampa

Livello bibliografico

Monografia

Nota di contenuto

Chapter 1. Introduction -- Chapter 2. Fixed-Wing UAV Model -- Chapter 3. Distributed FTCC of Multi-UAVs With Prescribed Performance -- Chapter 4. Distributed FTCC of Multi-UAVs Under Actuator Fault and Input Saturation -- Chapter 5. Distributed FTCC of Multi-UAVs With Multiple Leader UAVs -- Chapter 6. Distributed Finite-Time FTCC of Multi-UAVs With Multiple Leader UAVs -- Chapter 7. Decentralized Finite-Time Attitude FTCC of Multi-UAVs With Prescribed

Performance -- Chapter 8. Decentralized Attitude FTCC of Multi-UAVs Under Directed Communication Topology -- Chapter 9. Decentralized FTCC of Multi-UAVs for Cooperative Forest Fire Monitoring -- Chapter 10. Conclusions and Future Directions.

Sommario/riassunto

This book focuses on the fault-tolerant cooperative control (FTCC) of multiple unmanned aerial vehicles (multi-UAVs). It provides systematic and comprehensive descriptions of FTCC issues in multi-UAVs concerning faults, external disturbances, strongly unknown nonlinearities, and input saturation. Further, it addresses FTCC design from longitudinal motions to attitude motions, and outer-loop position motions of multi-UAVs. The book's detailed control schemes can be used to enhance the flight safety of multi-UAVs. As such, the book offers readers an in-depth understanding of UAV safety in cooperative/formation flight and corresponding design methods. The FTCC methods presented here can also provide guidelines for engineers to improve the safety of aerospace engineering systems. The book offers a valuable asset for scientists and researchers, aerospace engineers, control engineers, lecturers and teachers, and graduates and undergraduates in the system and control community, especially those working in the field of UAV cooperation and multi-agent systems.
