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Nota di contenuto	Interpersonal Maps: How to Map Affordances for Interaction Behaviour -- Does It Help a Robot Navigate to Call Navigability an Affordance? -- Learning Causality and Intentional Actions -- GrAM: Reasoning with Grounded Action Models by Combining Knowledge Representation and Data Mining -- Affordance-Based Human-Robot Interaction -- Reinforcement Learning of Predictive Features in Affordance Perception -- A Functional Model for Affordance-Based Agents -- Affordances in an Ecology of Physically Embedded Intelligent Systems -- Use of Affordances in Geospatial Ontologies -- Learning the Affordances of Tools Using a Behavior-Grounded Approach -- Function-Based Reasoning for Goal-Oriented Image Segmentation -- The MACS Project: An Approach to Affordance-Inspired Robot Control.