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Sommario/riassunto	Robotics is an important part of modern engineering involving electricity and electronics, computers, mathematics, and mechanism design. In recent years, in addition to serial robots, multi-robot systems have begun to attract the attention of students, academics, and industry workers. This interest has directly impacted the development of novel theoretical research areas and products. This book explores new developments in multi-robot systems, such as trajectory planning, control algorithms, and programming.