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Sommario/riassunto	This book discusses the state estimation and stabilization of nonlinear systems, focusing on both theoretical and practical aspects. It aims to provide comprehensive insights into various stability concepts,

particularly practical h-stability, using Lyapunov stability theory. The editors and contributors present new methods and sufficient conditions for ensuring stability in nonlinear impulsive systems, with applications across fields such as engineering, biology, and economics. The book is intended for researchers, practitioners, and students in systems control and related disciplines.