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Altri autori (Persone)	HammamiMohamed Ali NaifarOmar
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Nota di contenuto	1.Practical hStability of Nonlinear Impulsive Systems: A Survey -- 2. Practical exponential stabilization for semi-linear systems in Hilbert spaces -- 3.An observer controller for delay impulsive switched systems -- 4.Stabilization of TS fuzzy systems via a practical observer -- 5.Observer-Based Robust Tracking Controller Design of Nonlinear Dynamic Systems Represented by Bilinear T-S Fuzzy Systems -- 6. H_infinity filter design for discrete-time switched interconnected systems with time delays -- 7.Stability and Observability Analysis of Uncertain Neutral Time-Delay Systems -- 8.Zonotopic State Estimation for Uncertain Discrete-Time Switched Linear Systems -- 9.Stability and stabilisation of nonlinear incommensurate fractional order difference systems -- 10.Nonlinear Fractional Discrete Neural Networks: Stability, Stabilization and Synchronization -- 11.LMI-based Designs for Feedback Stabilization of Linear/ Nonlinear Discrete-Time Systems in

Reciprocal State Space: Synthesis and Experimental Validation -- 12.  
 Overview on active fault-tolerant control -- 13. The nonlinear  
 Progressive Accommodation: Design and methodology -- 14. Linear  
 Methods For Stabilization and Synchronization h-Fractional Chaotic  
 Maps -- 15. Artificial Neural Network design for non linear Takagi-  
 Sugeno systems: Application to Tracking of trajectory, state and fault  
 estimation of MIABOT robot -- 16. Sliding mode fault tolerant control  
 against actuator failures for UAVs. -- 17. Frequency Stabilization in  
 Microgrid using Super Twisting Sliding Mode -- 18. Determination of  
 the dynamic parameters of the planar robot with 2 degrees of freedom  
 by the method of least squares and instrumental variables -- 19. Design  
 and Analysis of Nonsingular Terminal Super Twisting Sliding Mode  
 Controller for Lower Limb Rehabilitation Exoskeleton Contacting with  
 ground -- 20. Generalized Predictive Control Design of Benchmark  
 Distillation Columns: A Case Study for Multi-Input Multi-Output System  
 -- 21. Robust EV's speed Tracking using fractional order controller --  
 22. Fractional order control of a grid connected WindPACT turbine --  
 23. Comparative study between PI Controller and Fractional Order PI for  
 speed control applied to the traction system of an Electric Vehicle (EV).

## Sommario/riassunto

This book presents the separation principle which is also known as the  
 principle of separation of estimation and control and states that, under  
 certain assumptions, the problem of designing an optimal feedback  
 controller for a stochastic system can be solved by designing an  
 optimal observer for the system's state, which feeds into an optimal  
 deterministic controller for the system. Thus, the problem may be  
 divided into two halves, which simplifies its design. In the context of  
 deterministic linear systems, the first instance of this principle is that if  
 a stable observer and stable state feedback are built for a linear time-  
 invariant system (LTI system hereafter), then the combined observer  
 and feedback are stable. The separation principle does not true for  
 nonlinear systems in general. Another instance of the separation  
 principle occurs in the context of linear stochastic systems, namely that  
 an optimum state feedback controller intended to minimize a quadratic  
 cost is optimal for the stochastic control problem with output  
 measurements. The ideal solution consists of a Kalman filter and a  
 linear-quadratic regulator when both process and observation noise are  
 Gaussian. The term for this is linear-quadratic-Gaussian control. More  
 generally, given acceptable conditions and when the noise is a  
 martingale (with potential leaps), a separation principle, also known as  
 the separation principle in stochastic control, applies when the noise is  
 a martingale (with possible jumps).