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Nota di contenuto	Introduction Basic L1 Adaptive Controller: A State Of The Art Study Hybrid L1 Adaptive Controller- I: Stochastic Optimization & Metaheuristics Based Approach Hybrid L1 Adaptive Controller- II: Fuzzy Parallel Distributed Compensation Based Approach Speed Control Of Electrical Actuator Angular Position Control Of Two Link Robot Manipulator Temperature Control Of Air Heater System Future Research Directions Of Hybrid Controller
Sommario/riassunto	This book details the designing of hybrid control strategies for practical systems containing time varying uncertainties, disturbances, nonlinearities, unknown parameters, unmodelled dynamics, delays, etc., concurrently. In this book, the advantages of different controllers will be brought together to produce superior control performance for the practical systems.