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> Framework to Enable Cooperation of Swarm Robots -- Collective Behavior for Swarm Robots with Distributed Learning -- Exploration of Underwater Environments with a Swarm of Heterogeneous Surface Robots -- Integrating Reinforcement Learning and Optimization Task: Evaluating an agent to dynamically select PSO communication topology

-- Filho Swarm Multi-agent Trapping Multi-target Control with Obstacle Avoidance -- A Novel Data Association Method for Multitarget Tracking Based on IACA -- MACT: Multi-agent Collision Avoidance with Continuous Transition Reinforcement Learning via

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Sommario/riassunto

This two-volume set LNCS 13968 and 13969 constitutes the proceedings of the 14th International Conference on Advances in Swarm Intelligence, ICSI 2023, which took place in Shenzhen, China, China, in July 2023. The theme of this year's conference was "Serving Life with Swarm Intelligence". The 81 full papers presented were carefully reviewed and selected from 170 submissions. The papers are organized into 12 cohesive sections covering major topics of swarm intelligence research and its development and applications. The papers of the first part cover topics such as: Swarm Intelligence Computing; Swarm Intelligence Optimization Algorithms; Particle Swarm Optimization Algorithms; Genetic Algorithms; Optimization Computing Algorithms; Neural Network Search & Large-Scale Optimization; Multiobjective Optimization.