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Autore	Moretti Valter
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Soggetti	Mathematics Mechanics, Applied
	Mechanics
	Mathematical physics
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Nota di hibliografia	Includes hibliographical references and index
Nota di contenuto	1 The Space and Time of Classical Physics 2 The Spacetime of Classical Physics and Classical Kinematics 3 Newtonian dynamics: a conceptual critical review 4 Balance equations and first integrals in Mechanics 5 Introduction to Rigid Body Mechanics 6 Introduction to stability theory with applications to Mechanics 7 Foundations of Lagrangian Mechanics 8 Symmetries and conservation laws in Lagrangian Mechanics 9 Advanced topics in Lagrangian Mechanics 10 Mathematical introduction to Special Relativity and the relativistic Lagrangian formulation 11 Fundamentals of Hamiltonian Mechanic 12 Canonical Hamiltonian theory, Hamiltonian symmetries and Hamilton-Jacobi theory 13 Hamiltonian symplectic structures: an introduction 14 Complement: elements of the theory of ordinary differential equations 15 Complement: the physical principles at the

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	in Differential Geometry Appendix C: Solutions and/or hints to suggested exercises.
Sommario/riassunto	This textbook aims at introducing readers, primarily students enrolled in undergraduate Mathematics or Physics courses, to the topics and methods of classical Mathematical Physics, including Classical Mechanics, its Lagrangian and Hamiltonian formulations, Lyapunov stability, plus the Liouville theorem and the Poincaré recurrence theorem among others. The material also rigorously covers the theory of Special Relativity. The logical-mathematical structure of the physical theories of concern is introduced in an axiomatic way, starting from a limited number of physical assumptions. Special attention is paid to themes with a major impact on Theoretical and Mathematical Physics beyond Analytical Mechanics, such as the Galilean symmetry of classical Dynamics and the Poincaré symmetry of relativistic Dynamics, the far- fetching relationship between symmetries and constants of motion, the coordinate-free nature of the underpinning mathematical objects, or the possibility of describing Dynamics in a global way while still working in local coordinates. Based on the author's established teaching experience, the text was conceived to be flexible and thus adapt to different curricula and to the needs of a wide range of students and instructors.