

1. Record Nr.	UNINA9910728940503321
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Titolo	Advances in Mechanism, Machine Science and Engineering in China : Proceedings of IFToMM CCMMS 2022 // edited by Xinjun Liu
Pubbl/distr/stampa	Singapore : , : Springer Nature Singapore : , : Imprint : Springer, , 2023
ISBN	9789811993985 9789811993978
Edizione	[1st ed. 2023.]
Descrizione fisica	1 online resource (2228 pages)
Collana	Lecture Notes in Mechanical Engineering, , 2195-4364
Disciplina	621
Soggetti	Machinery Manufactures Mechatronics Machinery and Machine Elements Machines, Tools, Processes
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Effect of Thermal and Mechanical Training in Twisted & Coiled Polymer Fiber (TCPF) Artificial Muscle for Improved Actuation Consistency -- Transmission Error Analysis of Planetary Gear Train Based on Probability Calculation -- Precision Motion Control of Separate Meter-in and Separate Meter-out Hydraulic Swing System with State Constraints.
Sommario/riassunto	This book presents the conference proceedings of the 23rd IFToMM China International Conference on Mechanism and Machine Science & Engineering (IFToMM CCMMS 2022). CCMMS was initiated in 1982, and it is the most important forum held in China for the exchange of research ideas, presentation of technical and scientific achievements, and discussion of future directions in the field of mechanism and machine science. The topics include parallel/hybrid mechanism synthesis and analysis, theoretical & computational kinematics, compliant mechanisms and micro/nano-mechanisms, reconfigurable and metamorphic mechanisms, space structures, mechanisms and materials, structure adaptation in space environment and ground testing, large-scale membrane deployable structures, construction and application of super-scale space systems, cams, gears and combining

mechanisms, fluid power mechatronics drivetrain, mechanical design theory and methods, dynamics and vibration control, mechatronics, biologically inspired mechanisms and robotics, medical & rehabilitation robotics, mobile robotics, soft robotics, heavy non-road mobile machine, robot applications, engineering education on mechanisms, machines, and robotics. This book provides a state-of-the-art overview of current advances in mechanism and machine science in China. The inspiring ideas presented in the papers enlighten academic research and industrial application. The potential readers include academic researchers and industrial professionals in mechanism and machine science. .
