Record Nr. UNINA9910725097803321 Autore Jongeneel Wouter Titolo Topological Obstructions to Stability and Stabilization [[electronic resource]]: History, Recent Advances and Open Problems // by Wouter Jongeneel, Emmanuel Moulay Cham:,: Springer Nature Switzerland:,: Imprint: Springer., 2023 Pubbl/distr/stampa **ISBN** 3-031-30133-1 Edizione [1st ed. 2023.] Descrizione fisica 1 online resource (134 pages) Collana SpringerBriefs in Control, Automation and Robotics, , 2192-6794 Altri autori (Persone) MoulayEmmanuel 629.8312 Disciplina 003 Soggetti Control engineering Dynamical systems **Topology** Robotics Algorithms Control and Systems Theory **Dynamical Systems** Design and Analysis of Algorithms Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Nota di contenuto 1. Introduction -- 2. General topology -- 3. Dierential topology -- 4. Algebraic topology -- 5. Dynamical control systems -- 6. Topological obstructions -- 7. Towards accepting and overcoming topological obstructions -- 8. Generalizations and open problems. . This open access book provides a unified overview of topological Sommario/riassunto obstructions to the stability and stabilization of dynamical systems defined on manifolds and an overview that is self-contained and accessible to the control-oriented graduate student. The authors review the interplay between the topology of an attractor, its domain of attraction, and the underlying manifold that is supposed to contain these sets. They present some proofs of known results in order to highlight assumptions and to develop extensions, and they provide new

results showcasing the most effective methods to cope with these

obstructions to stability and stabilization. Moreover, the book shows how Borsuk's retraction theory and the index-theoretic methodology of Krasnosel'skii and Zabreiko underlie a large fraction of currently known results. This point of view reveals important open problems, and for that reason, this book is of interest to any researcher in control, dynamical systems, topology, or related fields.