

1.	Record Nr.	UNISALENTO991003666819707536
	Autore	Pinelli, Gian Vincenzo
	Titolo	Un abbozzo di grammatica francese del '500 : le note di Gian Vincenzo Pinelli / introduzione, testo critico e note a cura di Anna Maria Rauge
	Pubbl/distr/stampa	Fasano : Schena, 1984
	Descrizione fisica	159 p. ; 21 cm
	Collana	Biblioteca della ricerca. Cultura straniera ; 1
	Altri autori (Persone)	Raugei, Anna Maria
	Disciplina	445
	Soggetti	Lingua francese - Grammatica
	Lingua di pubblicazione	Italiano
	Formato	Materiale a stampa
	Livello bibliografico	Monografia
2.	Record Nr.	UNINA9910696719703321
	Titolo	Medicaid [[electronic resource]] : CMS needs more information on the billions of dollars spent on supplemental payments : report to the Ranking Member, Committee on Finance, U.S. Senate
	Pubbl/distr/stampa	[Washington, D.C.] : , : U.S. Govt. Accountability Office, , [2008]
	Descrizione fisica	iv, 76 pages : digital, PDF file
	Soggetti	Medicaid
	Lingua di pubblicazione	Inglese
	Formato	Materiale a stampa
	Livello bibliografico	Monografia
	Note generali	Title from title screen (viewed on July 9, 2008). "May 2008." Paper version available from: U.S. Govt. Accountability Office, 441 G St., NW, Rm. LM, Washington, D.C. 20548. "GAO-08-614."

Nota di bibliografia	Includes bibliographical references.
3. Record Nr.	UNINA9910741179703321
Autore	Abdessameud Abdelkader
Titolo	Motion coordination for VTOL unmanned aerial vehicles : attitude synchronisation and formation control / / Abdelkader Abdessameud, Abdelhamid Tayebi
Pubbl/distr/stampa	New York, : Springer, 2013
ISBN	1-4471-5094-5
Edizione	[1st ed. 2013.]
Descrizione fisica	1 online resource (xv, 182 pages) : illustrations (some color)
Collana	Advances in industrial control
Altri autori (Persone)	TayebiAbdelhamid
Disciplina	623 629.132/6 629.1326
Soggetti	Drone aircraft - Control systems Aeronautics
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	"ISSN: 1430-9491."
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Background and Preliminaries -- Mathematical Models of Flying Vehicles -- Attitude Synchronization -- Attitude Synchronization with Communication Delays -- Global Trajectory Tracking of VTOL UAVs -- Formation Control of VTOL UAVs -- Formation Control with Communication Delays.
Sommario/riassunto	Motion Coordination for VTOL Unmanned Aerial Vehicles develops new control design techniques for the distributed coordination of a team of autonomous unmanned aerial vehicles. In particular, it provides new control design approaches for the attitude synchronization of a formation of rigid body systems. In addition, by integrating new control design techniques with some concepts from nonlinear control theory and multi-agent systems, it presents a new theoretical framework for the formation control of a class of under-actuated aerial vehicles capable of vertical take-off and landing. Several practical problems related to the systems' inputs, states measurements, and restrictions on the interconnection topology between the aerial vehicles in the team are addressed. Worked examples with sufficient details and

simulation results are provided to illustrate the applicability and effectiveness of the theoretical results discussed in the book. The material presented is primarily intended for researchers and industrial engineers from robotics, control engineering and aerospace communities. It also serves as a complementary reading for graduate students involved in research related to flying robotics, aerospace, control of under-actuated systems, and nonlinear control theory.
