

1. Record Nr.	UNINA9910450389003321
Titolo	Street addressing and the management of cities [[electronic resource] /] / Catherine Farvacque-Vitkovic ... [et al.]
Pubbl/distr/stampa	Washington, DC, : World Bank, c2005
ISBN	1-280-14951-5 9786610149513 0-8213-5816-2
Descrizione fisica	1 online resource (284 p.)
Collana	Directions in development
Disciplina	388.4/11
Soggetti	Urban economics Electronic books. Africa Economic conditions
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Bibliographic Level Mode of Issuance: Monograph

2. Record Nr.	UNINA9910692139003321
Titolo	Air [[electronic resource]] : Region 10's oversight of Washington state's air compliance and enforcement program
Pubbl/distr/stampa	[Washington, D.C.] : , : United States Environmental Protection Agency, Office of Inspector General, , [1998]
Collana	Audit report
Soggetti	Air quality management - Washington (State)
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Title from title screen (viewed on Jan. 6, 2004). "March 30, 1998." "E1KAF7-10-0015-8100094."
Nota di bibliografia	Includes bibliographical references.

3. Record Nr.	UNINA9910143888103321
Autore	Beetz Michael
Titolo	Plan-Based Control of Robotic Agents : Improving the Capabilities of Autonomous Robots / / by Michael Beetz
Pubbl/distr/stampa	Berlin, Heidelberg : , : Springer Berlin Heidelberg : , : Imprint : Springer, , 2002
ISBN	3-540-36381-5
Edizione	[1st ed. 2002.]
Descrizione fisica	1 online resource (XI, 194 p.)
Collana	Lecture Notes in Artificial Intelligence ; ; 2554
Disciplina	629.892
Soggetti	Robotics Automation Artificial intelligence Computer science Computer networks Computers, Special purpose Automatic control Mechatronics Robotics and Automation Artificial Intelligence Computer Science, general Computer Communication Networks Special Purpose and Application-Based Systems Control, Robotics, Mechatronics
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Bibliographic Level Mode of Issuance: Monograph
Nota di bibliografia	Includes bibliographical references.
Nota di contenuto	Overview of the Control System -- Plan Representation for Robotic Agents -- Probabilistic Hybrid Action Models -- Learning Structured Reactive Navigation Plans -- Plan-Based Robotic Agents -- Conclusions.
Sommario/riassunto	Robotic agents, such as autonomous office couriers or robot tourguides, must be both reliable and efficient. Thus, they have to flexibly interleave their tasks, exploit opportunities, quickly plan their course of action, and, if necessary, revise their intended activities. This

book makes three major contributions to improving the capabilities of robotic agents: - first, a plan representation method is introduced which allows for specifying flexible and reliable behavior - second, probabilistic hybrid action models are presented as a realistic causal model for predicting the behavior generated by modern concurrent percept-driven robot plans - third, the system XFRMLEARN capable of learning structured symbolic navigation plans is described in detail.
