

1. Record Nr.	UNINA9910667495603321
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Titolo	Global positioning systems [[electronic resource] /] / Viggo Asphaug and Elias Sorensen, editors
Pubbl/distr/stampa	New York, : Nova Science Publishers, c2010 [Washington, D.C.] : , : U.S. Department of the Interior, National Park Service, Cultural Resources, Park Historic Structures & Cultural Landscapes, , [1998?]
ISBN	1-61324-734-6
Descrizione fisica	1 online resource (259 p.)
Collana	Space science, exploration and policies
Altri autori (Persone)	SorensenElias
Disciplina	910.285
Soggetti	Global Positioning System Distances United States
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	""GLOBAL POSITIONING SYSTEMS ""; ""GLOBAL POSITIONING SYSTEMS""; ""CONTENTS ""; ""PREFACE""; ""HIGHER ORDER IONOSPHERIC ERRORS IN MODERNIZED GPS AND FUTURE GALILEO SYSTEMS""; ""Abstract""; ""Introduction""; ""Higher Order Ionospheric Effects""; ""Ionospheric Refractive Index""; ""Ionospheric Phase and Group Delays""; ""Ionospheric Effects on GNSS Observables""; ""Higher Order Effects Computation""; ""Third Order Residual Error""; ""Error due to TEC Difference""; ""Error due to Excess Path Length""; ""Residual Range Error in the Phase Combination"" ""Residual Range Error in the Code Combination""""Higher Order Effects Correction""; ""Residual Error (I?stEC)tr Correction""; ""Residual Error (I?st3)tr Correction""; ""Excess Path Length (I?stlen)tr Correction""; ""Quadruple-Frequency Combination""; ""New Dual-Frequency Combinations""; ""Impact of Ionosphere Free Combination""; ""Conclusion""; ""References""; ""HIGHWAY GEOMETRY DETERMINATION FROM GPS DATA""; ""Abstract""; ""Introduction""; ""Case Study""; ""GPS Devices""; ""Data Collection""; ""Data Post-Processing""; ""Determination of the Roadway Centerline""; ""Comparative Study"" ""Conclusion""""Acknowledgements""; ""References""; ""HOW LOCATION

PERFORMANCE INDEXES OF GPS RADIO COLLAR REFLECT LOCATION
ERRORIN MOUNT FUJI, CENTRAL JAPAN"; ""Abstract"; ""Introduction";
""Methods"; ""Study Area"; ""Location Performance Tests"; ""Data
Analyses"; ""Results"; ""Summary of Location"; ""Relationships among
Location Performance Indexes"; ""Discussion"; ""Acknowledgements";
""References"
""APPLICATION OF A GEOGRAPHICAL INFORMATION SYSTEM (GIS) AND
THE GLOBAL POSITIONING SYSTEM (GPS) TO DENGUE VIRUS VECTOR:
AEDES MOSQUITOES DISTRIBUTION IN AN EPIDEMIC AREA OF
THAILAND, A TECHNICAL COMMENT""""Abstract"; ""Introduction";
""Technical Comment"; ""1. Study Design"; ""2. Results""; ""3.
Discussion""; ""References""; ""ACCURATE GPS-BASED GUIDANCE OF
AGRICULTURAL VEHICLES OPERATING ON SLIPPERY GROUND"";
""Abstract""; ""1. Introduction""; ""2. Experimental Context""; ""3. Vehicle
Modeling""; ""3.1. Modeling Assumptions and Notations""
""3.2. Vehicle Modeling under Non-sliding Assumption""""3.3. Vehicle
Modeling Accounting for Sliding Effects""; ""3.4.Measurement and
Estimation of Vehicle Variables""; ""3.4.1. Direct Measurement of the
Vehicle Location""; ""3.4.2. Reconstruction of the Vehicle Heading"";
""3.4.3. Estimation of the Sliding Variables""; ""4. Path Following Control
Law Design""; ""4.1. Non-linear Control in Absence of Sliding""; ""4.1.1.
Conversion of Vehicle Model (10) into Chained Form""; ""4.1.2. Non-
linear Control Law Design""; ""4.2. Internal Model Adaptive Control
Accounting for Sliding Effects""
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