1. Record Nr. UNINA9910623996503321 Autore Kim Kyoung-Yun **Titolo** Flexible Automation and Intelligent Manufacturing: The Human-Data-Technology Nexus: Proceedings of FAIM 2022, June 19–23, 2022, Detroit, Michigan, USA / / edited by Kyoung-Yun Kim, Leslie Monplaisir, Jeremy Rickli Cham:,: Springer International Publishing:,: Imprint: Springer,, Pubbl/distr/stampa 2023 **ISBN** 3-031-18326-6 Edizione [1st ed. 2023.] Descrizione fisica 1 online resource (XVII, 414 p. 208 illus., 174 illus. in color.) Collana Lecture Notes in Mechanical Engineering, , 2195-4364 Disciplina 629.8 Soggetti Industrial engineering Automation Robotics Production engineering Computer-aided engineering **Industrial Automation** Robotic Engineering **Process Engineering** Computer-Aided Engineering (CAD, CAE) and Design Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia Intro -- Preface -- FAIM 2022 Organization -- Organizing Committee Nota di contenuto -- General Chairs -- Technical Program Chairs -- Industrial Program Chairs -- Communication and Media Chairs -- Conference Managers -- Assistant Conference Managers -- Steering Committee - FAIM 2022 -- Advisory Board - Program Committee -- Honorary Chairs --Scientific Committee -- Contents -- Manufacturing Processes -- Die-Less Forming of Fiber-Reinforced Plastic Composites -- 1 Introduction -- 2 Related Work -- 3 Process Analysis for Die-Less Forming -- 3.1 Materials -- 3.2 Requirements and Functional Analysis -- 3.3 Allocation and Evaluation of the Processing Functions -- 4 Preliminary

Practical Experiments -- 4.1 Liquid Separate Thermoset Processing -- 4.2 Organo Sheet Forming -- 4.3 Woven Commingled Yarn Processing

-- 5 Discussion and Outlook -- References -- Assessment of High Porosity Lattice Structures for Lightweight Applications -- 1 Introduction -- 2 Modelling and Assessment of Lattice Structures --2.1 Modelling of Lattice Structures -- 2.2 Numerical Assessment -- 3 Manufacturing and Dimensional Assessment of Lattice Structures -- 3.1 Manufacturing with FDM Printer -- 3.2 Dimensional Assessment of 3D Printed Cellular Structures -- 4 Conclusions -- References -- Machine Tools -- Development of a Sensor Integrated Machining Vice Towards a Non-invasive Milling Monitoring System -- 1 Introduction -- 2 State of the Art -- 3 Approach -- 4 Case Study on Chatter Detection -- 5 Results and Discussion -- 6 Conclusions -- References -- Effect of Ultrasonic Burnishing Parameters on Burnished-Surface Quality of Stainless Steel After Heat Treatment -- 1 Introduction -- 2 Materials and Methods -- 2.1 Surface Roughness -- 2.2 Surface Hardness -- 2.3 EBSD (Sample Preparation and Post Processing) -- 3 Results and Discussion -- 3.1 Surface Roughness -- 3.2 Surface Hardness. 3.3 Grainsize Characterization -- 4 Conclusions -- References -- High Precision Fabrication of an Innovative Fiber-Optic Displacement Sensor -- 1 Introduction -- 2 Sensor Principle -- 3 High Precision Machining Technique -- 3.1 The High Precision Turning Machine -- 3.2 The Machining Strategy of the Cones Assembled Grating -- 4 Conclusion --References -- 3D Printing of Hydrogel-Based Seed Planter for In-Space Seed Nursery -- 1 Introduction -- 2 Materials and Method -- 2.1 Materials -- 2.2 Hydrogel Printing -- 2.3 Seed Planting -- 3 Results and Discussion -- 3.1 Hydrogel Printing Quality Control and Mass Evaluation -- 3.2 Volume Evaluation -- 3.3 Soybean Density Evaluation -- 4 Conclusions -- References -- Modelling and Simulation of Automated Hydraulic Press Brake -- 1 Introduction -- 2 Methodology -- 2.1 Computer Aided Modelling and Simulation -- 2.2 Model Control of Triplet Cylinder -- 2.3 The Operational Model of the Triplet Cylinder -- 3 Results and Discussion -- 4 Conclusion --References -- Assessment of Reconfigurable Vibrating Screen Technology for the Mining Industries -- 1 Introduction -- 2 Methodology -- 3 Results and Discussion -- 4 Conclusion --References -- Manufacturing Systems -- Deep Anomaly Detection for Endoscopic Inspection of Cast Iron Parts -- 1 Introduction -- 2 Related Work -- 2.1 One-Class Classification (OCC) for Visual Anomaly Detection -- 2.2 One-Class Classification Anomaly Detection for Industrial Inspection -- 3 Use Case 'Endoscopic Cavity Inspection of Cast Iron Part' -- 4 Proposed Approach -- 4.1 Experimental Setup --4.2 Experimental Results -- 4.3 Threshold Selection and Comparison with Supervised Learning -- 4.4 Discussion -- 5 Conclusion and Outlook -- References -- Classification and Detection of Malicious Attacks in Industrial IoT Devices via Machine Learning -- 1 Introduction -- 2 Background. 3 Dataset and Methodology -- 4 Results and Discussion -- 5 Conclusion -- References -- Implementation of a Novel Fully Convolutional Network Approach to Detect and Classify Cyber-Attacks on IoT Devices in Smart Manufacturing Systems -- 1 Introduction -- 2 Preprocessing of Datasets -- 3 Results and Analysis -- 4 Conclusions -- References -- Application of ARIMA-LSTM for Manufacturing Decarbonization Using 4IR Concepts -- 1 Introduction -- 2 Related Work on ARIMA-LSTM -- 3 Methodology -- 3.1 Data Set

and Processing -- 3.2 Auto-regressive Integrated Moving Average (ARIMA) -- 3.3 Long Short-Term Memory (LSTM) -- 3.4 Hybrid ARIMA-LSTM -- 3.5 Predictive Evaluation Indicators Validation -- 4 Results -- 5 Conclusion -- References -- Online Path Planning in a Multi-agent-Controlled Manufacturing System -- 1 Introduction -- 2 Manufacturing

Scenario -- 3 Design and Implementation -- 4 Conclusion --References -- Assessing Visual Identification Challenges for Unmarked and Similar Aircraft Components -- 1 Introduction -- 2 Related Work and State of the Art -- 3 Assessing Identification Challenges -Methodology -- 4 Application of Methodology to Use-Cases -- 4.1 Use-Case 1 - Type-Identification of Bushings -- 4.2 Use-Case 2 -Identification of Tubes -- 5 Discussion -- 6 Conclusion and Outlook --References -- Projecting Product-Aware Cues as Assembly Intentions for Human-Robot Collaboration -- 1 Introduction -- 2 Related Work --3 Research Objectives, Setting and Scope -- 4 Theoretical Background -- 4.1 Oriented Minimum Bounding Boxes -- 4.2 Camera and Projector Model -- 5 Methods -- 5.1 Estimating Intrinsic and Extrinsic Parameters -- 5.2 Digital Thread Framework -- 5.3 Product Design Environment -- 5.4 Intent Projection -- 6 Experimental Results and Observations -- 6.1 Occlusions -- 6.2 Bounding Boxes for Intent Projection -- 6.3 Digital Thread Framework. 7 Conclusions and Future Work -- References -- Online Quality Inspection Approach for Submerged Arc Welding (SAW) by Utilizing IR-RGB Multimodal Monitoring and Deep Learning -- 1 Introduction -- 2 Quality Assessment Method -- 2.1 Model Selection and Architecture --2.2 Training of the CNNs -- 3 Experimental Setup and Data Processing -- 4 Results and Discussion -- 5 Conclusions and Future Outlook --References -- Detachable, Low-Cost Tool Holder for Grippers in Human-Robot Interaction -- 1 Introduction -- 2 State-of-the-Art -- 3 Development Process -- 4 Detachable, Low-Cost Tool Holder for Robot Grippers -- 5 Discussion -- 6 Conclusion and Outlook -- References -- Intelligent Robotic Arm Path Planning (IRAP2) Framework to Improve Work Safety in Human-Robot Collaboration (HRC) Workspace Using Deep Deterministic Policy Gradient (DDPG) Algorithm -- 1 Introduction -- 2 Problem Statement and Methodology -- 2.1 Problem Statement --2.2 The IRAP2 Framework Based on DDPG -- 3 Results and Discussion -- 3.1 Evaluation of the Training Process -- 3.2 The Optimal Pick-Up Path Generated by IRAP2 Framework -- 3.3 Validation of the Robot Control -- 4 Conclusion and Outlook -- References -- A Conceptual Framework of a Digital-Twin for a Circular Meat Supply Chain -- 1 Introduction -- 2 Background -- 3 A Conceptual Framework of Digital-Twin for a Circular Meat Supply Chain -- 3.1 Proposed Conceptual Framework of DT Applied to a Circular Meat Supply Chain -- 4 Conclusions and Future Challenges/Work -- References --A Mathematical Model for Cloud-Based Scheduling Using Heavy Traffic Limit Theorem in Queuing Process -- 1 Introduction -- 2 Cloud Manufacturing Platform -- 3 Methodology -- 3.1 Heavy Traffic Limit Theory in Different Classified QoS -- 4 Modelling of Queuing Process Based on Cloud Classification -- 4.1 Number of Operational Resources in the Queuing System. 5 Results and Discussion -- 6 Conclusion -- References -- Approach for Evaluating Changeable Production Systems in a Battery Module Production Use Case -- 1 Introduction -- 2 Industry Survey -- 2.1 Survey Structure -- 2.2 Survey Results -- 3 State of the Art -- 4 Method -- 5 Battery Module Production Use Case -- 6 Summary and Outlook -- References -- Cost-Minimal Selection of Material Supply Strategies in Matrix Production Systems -- 1 Introduction -- 2 State of the Art -- 2.1 Material Supply and the Selection Process of Supply Strategies -- 2.2 Challenges to the Material Supply in Matrix Production -- 2.3 Cost Accounting in the Context of Logistics -- 2.4 Algorithms -- 3 Method for Cost-Minimal Material Supply Strategy Selection -- 3.1 Structure of Method -- 3.2 Cost Side Description

of Alternative Supply Strategies -- 3.3 Selection of the Most Cost-

Effective Material Supply Strategy in Matrix Production System -- 4 Summary and Outlook -- References -- Assessment of Ergonomics Risk Experienced by Welding Workers in a Rail Component Manufacturing Organization -- 1 Introduction -- 2 Methods and Materials -- 3 Results and Interpretation -- 4 Conclusion --References -- A Survey of Smart Manufacturing for High-Mix Low-Volume Production in Defense and Aerospace Industries -- 1 Introduction -- 2 Manufacturing Strategies for HMLV in Defense and Aerospace Industries -- 2.1 Major Issues -- 2.2 Advanced Processing Techniques -- 2.3 Make-to-X Strategy -- 2.4 Group Technology -- 2.5 Lean Practices -- 3 A Smart Manufacturing Solution -- 3.1 Automation in Manufacturing -- 3.2 Smart Production Planning and Control -- 4 Concluding Remarks -- References -- Feasibility Analysis of Safety Training in Human-Robot Collaboration Scenario: Virtual Reality Use Case -- 1 Introduction -- 2 Related Work -- 2.1 Virtual Reality Training -- 2.2 Virtual Reality Safety Training. 3 Research Methods, Material and Approach.

Sommario/riassunto

This is an open access book. It gathers the first volume of the proceedings of the 31st edition of the International Conference on Flexible Automation and Intelligent Manufacturing, FAIM 2022, held on June 19 – 23, 2022, in Detroit, Michigan, USA, Covering four thematic areas including Manufacturing Processes, Machine Tools, Manufacturing Systems, and Enabling Technologies, it reports on advanced manufacturing processes, and innovative materials for 3D printing, applications of machine learning, artificial intelligence and mixed reality in various production sectors, as well as important issues in human-robot collaboration, including methods for improving safety. Contributions also cover strategies to improve quality control, supply chain management and training in the manufacturing industry, and methods supporting circular supply chain and sustainable manufacturing. All in all, this book provides academicians, engineers and professionals with extensive information on both scientific and industrial advances in the converging fields of manufacturing, production, and automation.