1. Record Nr. UNINA9910619469203321 Autore Hamid Umar Zakir Abdul Titolo Feasible, Robust and Reliable Automation and Control for Autonomous Systems MDPI - Multidisciplinary Digital Publishing Institute, 2022 Pubbl/distr/stampa **ISBN** 3-0365-5076-3 Descrizione fisica 1 electronic resource (232 p.) Soggetti Technology: general issues History of engineering & technology Lingua di pubblicazione Inglese **Formato** Materiale a stampa Livello bibliografico Monografia The Special Issue book focuses on highlighting current research and Sommario/riassunto developments in the automation and control field for autonomous systems as well as showcasing state-of-the-art control strategy approaches for autonomous platforms. The book is co-edited by distinguished international control system experts currently based in Sweden, the United States of America, and the United Kingdom, with contributions from reputable researchers from China, Austria, France, the United States of America, Poland, and Hungary, among many others. The editors believe the ten articles published within this Special Issue will be highly appealing to control-systems-related researchers in applications typified in the fields of ground, aerial, maritime vehicles,

and robotics as well as industrial audiences.