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Sommario/riassunto	This book is a comprehensive introduction to model predictive control (MPC), including its basic principles and algorithms, system analysis and design methods, strategy developments and practical applications. The main contents of the book include an overview of the development trajectory and basic principles of MPC, typical MPC algorithms, quantitative analysis of classical MPC systems, design and tuning methods for MPC parameters, constrained multivariable MPC algorithms and online optimization decomposition methods. Readers will then progress to more advanced topics such as nonlinear MPC and its related algorithms, the diversification development of MPC with respect to control structures and optimization strategies, and robust MPC. Finally, applications of MPC and its generalization to optimization-based dynamic problems other than control will be discussed. Systematically introduces fundamental concepts, basic algorithms, and applications of MPC Includes a comprehensive overview of MPC development, emphasizing recent advances and modern approaches Features numerous MPC models and structures, based on rigorous research Based on the best-selling Chinese edition, which is a

key text in China Predictive Control: Fundamentals and Developments is written for advanced undergraduate and graduate students and researchers specializing in control technologies. It is also a useful reference for industry professionals, engineers, and technicians specializing in advanced optimization control technology.
