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Nota di contenuto	Frontmatter 1 Indice 7 Nota preliminar 9 Introduccion 11 La Revolucion rusa y su eco latinoamericano 18 El partido mundial y America Latina 28 La reeducacion de los cuadros de America Latina 34 La izquierda latinoamericana en la Guerra Fria 44 Venezuela: inicio del giro a la izquierda 48 Perfiles de la Revolucion bolivariana 54 El bolivarismo mas alla de Venezuela 73 Lecciones de las ultimas decadas: errores que deben evitarse 80 Consideraciones finales 90 Epilogo 97 Bibliografia 100 Autor 105
Sommario/riassunto	Los regimenes progresistas se encuentran en una profunda crisis. Quien no se contenta con denunciar las previsibles maquinaciones del » imperialismo«, debe buscar las razones internas del fracaso del proclamado »socialismo del siglo XXI«. ¿Por que tales regimenes, que deben su aparicion y sus exitos iniciales en gran medida a la movilizacion de las masas, no han podido mantener el apoyo activo de una mayoria de la poblacion? La respuesta se busca aqui recurriendo al historial de la izquierda latinoamericana. El objetivo es mostrar como el concepto organizativo de Lenin ha llegado a America Latina, comenzando con las intervenciones de la Internacional Comunista. Se examina si este legado tambien ha influido en los protagonistas del »

progresismo» y de que manera. La reflexion en la parte principal se basa en el papel central de Hugo Chavez y su relacion ambivalente con la herencia historica de la izquierda.

2. Record Nr.	UNINA9910523789003321
Titolo	4th EAI International Conference on Robotic Sensor Networks // edited by Shenglin Mu, Li Yujie, Huimin Lu
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Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Introduction -- A Mobile Robotic System for Rescue and Surveillance in Indoor Environment -- Study on the Learning in Intelligent Control using Neural Networks based on Back-Propagation and Differential Evolution -- Word Sense Disambiguation Graph-Based and Knowledge Base -- GDP Carbon Emission Prediction Base on Grey Model and Neural Network -- Automatic optimization of YOLOV3 image classification and positioning based on particle swarm optimization algorithm -- Contour Mask and Matting Driven Face Image Generation -- Eye-interface System using Convolutional Neural Networks for People with Physical Disabilities -- Proposal of Omnidirectional Movable Positioning Plate Using T-shaped Omni Wheel -- A general

pseudo-random number generator based on chaos -- A Light chaotic encryption algorithm for real-time video encryption -- Intelligent Analysis and Presentation of IOT Image Collection in Private Cloud -- Conclusion.

Sommario/riassunto

This book presents papers presented at the 4th EAI International Conference on Robotic Sensor Networks. The conference explored the integration of networks and robotic technologies, which has become a topic of increasing interest for both researchers and developers from academic fields and industries worldwide. The authors explore how big networks are becoming the main tool for the next generation of robotic research, owing to the explosive number of networks models and the increased computational power of computers. The papers discuss how these trends significantly extend the number of potential applications for robotic technologies while also bringing new challenges to the networks' communities. The 2nd EAI International Conference on Robotic Sensor Networks was held online on November 21-22, 2020. Presents the proceedings from 4th EAI International Conference on Robotic Sensor Networks, which took place November 21-22, 2020; Features papers on topics ranging from robotics in medicine to robotics in rescue and surveillance; Includes perspectives from a multi-disciplinary selection of global researchers, academics, and professionals.
