

1. Record Nr.	UNINA9910797050803321
Titolo	Invasive alien species : a new synthesis // edited by Harold A. Mooney [and five others]
Pubbl/distr/stampa	Washington ; ; Covelo ; ; London : , : Island Press, , [2005] ©2005
ISBN	1-59726-288-9
Descrizione fisica	1 online resource (392 pages)
Collana	SCOPE ; ; Volume 63
Disciplina	363.78
Soggetti	Nonindigenous pests - Control
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Bibliographic Level Mode of Issuance: Monograph
Nota di contenuto	Intro -- Title Page -- Copyright Page -- Table of Contents -- List of Figures, Tables, and Boxes -- Preface -- Acknowledgments -- Chapter 1: Invasive Alien Species: The Nature of the Problem -- Chapter 2: The Economics of Biological Invasions -- Chapter 3: Vector Science and Integrated Vector Management in Bioinvasion Ecology: Conceptual Frameworks -- Chapter 4: The ISSG Global Invasive Species Database and Other Aspects of an Early Warning System -- Chapter 5: Characterizing Ecological Risks of Introductions and Invasions -- Chapter 6: Ecology of Invasive Plants: State of the Art -- Chapter 7: Facilitation and Synergistic Interactions between Introduced Aquatic Species -- Chapter 8: Assessing Biotic Invasions in Time and Space: The Second Imperative -- Chapter 9: Best Practices for the Prevention and Management of Invasive Alien Species -- Chapter 10: Legal and Institutional Frameworks for Invasive Alien Species -- Chapter 11: Human Dimensions of Invasive Alien Species -- Chapter 12: Invasive Species in a Changing World: The Interactions between Global Change and Invasives -- Chapter 13: A Global Strategy on Invasive Alien Species: Synthesis and Ten Strategic Elements -- List of Contributors -- SCOPE Series List -- SCOPE Executive Committee -- Index.

2. Record Nr.	UNINA9910484621203321
Autore	Bingi Kishore
Titolo	Fractional-order Systems and PID Controllers : Using Scilab and Curve Fitting Based Approximation Techniques / / by Kishore Bingi, Rosdiazli Ibrahim, Mohd Noh Karsiti, Sabo Miya Hassan, Vivekananda Rajah Harindran
Pubbl/distr/stampa	Cham : , : Springer International Publishing : , : Imprint : Springer, , 2020
ISBN	3-030-33934-3
Edizione	[1st ed. 2020.]
Descrizione fisica	1 online resource (267 pages) : illustrations (some color), charts
Collana	Studies in Systems, Decision and Control, , 2198-4190 ; ; 264
Disciplina	629.8
Soggetti	Control engineering Computational intelligence System theory Control theory Control and Systems Theory Computational Intelligence Systems Theory, Control
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	Introduction -- Fractional-order Set-point Weighted Controllers and Approximation Techniques -- Fractional-order Set-point Weighted Controllers -- Approximation Techniques -- Scilab Toolbox For Fractional-order Systems and Controllers -- Scilab Based Toolbox For Fractional-order Systems and PID Controllers -- Scilab Based Toolbox for Fractional-order Chaotic Systems -- Appendix -- Index.
Sommario/riassunto	This book presents a detailed study on fractional-order, set-point, weighted PID control strategies and the development of curve-fitting-based approximation techniques for fractional-order parameters. Furthermore, in all the cases, it includes the Scilab-based commands and functions for easy implementation and better understanding, and to appeal to a wide range of readers working with the software. The presented Scilab-based toolbox is the first toolbox for fractional-order systems developed in open-source software. The toolboxes allow time

and frequency domains as well as stability analysis of the fractional-order systems and controllers. The book also provides real-time examples of the control of process plants using the developed fractional-order based PID control strategies and the approximation techniques. The book is of interest to readers in the areas of fractional-order controllers, approximation techniques, process modeling, control, and optimization, both in industry and academia. In industry, the book is particularly valuable in the areas of research and development (R&D) as well as areas where PID controllers suffice – and it should be noted that around 80% of low-level controllers in industry are PID based. The book is also useful where conventional PIDs are constrained, such as in industries where long-term delay and non-linearity are present. Here it can be used for the design of controllers for real-time processes. The book is also a valuable teaching and learning resource for undergraduate and postgraduate students.
