1.	Record Nr.	UNINA9910484408503321
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	Titolo	Automatic Control with Experiments / / by Victor Manuel Hernández-Guzmán, Ramón Silva-Ortigoza
	Pubbl/distr/stampa	Cham : , : Springer International Publishing : , : Imprint : Springer, , 2019
	ISBN	3-319-75804-7
	Edizione	[1st ed. 2019.]
	Descrizione fisica	1 online resource (XVI, 992 p. 633 illus., 91 illus. in color.)
	Collana	Advanced Textbooks in Control and Signal Processing, , 1439-2232
	Disciplina	629.8
	Soggetti	Automatic control
		System theory
		Power electronics
		Industrial engineering
		Production engineering
		Control and Systems Theory
		Systems Theory, Control
		Power Electronics, Electrical Machines and Networks
		Industrial and Production Engineering
	Lingua di pubblicazione	Inglese
	Formato	Materiale a stampa
	Livello bibliografico	Monografia
	Nota di contenuto	Chapter 1: Introduction -- Chapter 2: Physical system modeling -- Chapter 3: Ordinary linear differential equations -- Chapter 4: Stability criteria and steady state error -- Chapter 5: Time response-based design -- Chapter 6: Frequency response-based design -- Chapter 7: The state variables approach -- Chapter 8: Advanced topics in control -- Chapter 9: Feedback electronic circuits -- Chapter 10: Velocity control of a PM brushed DC motor -- Chapter 11: Position control of a PM brushed DC motor -- Chapter 12: Control of a servomechanism with flexibility -- Chapter 13: Control of a magnetic levitation system -- Chapter 14: Control of a ball and beam system -- Chapter 15: Control of a Furuta pendulum -- Chapter 16: Control of an inertia wheel pendulum -- A: Fourier and Laplace transforms -- B: Bode diagrams -- C: Decibels, dB -- D: Magnetically coupled coils -- E: Euler-Lagrange equations subject to constraints -- F: Numerical

implementation of controllers -- G: MATLAB/Simulink code used for some simulations -- Index.

| Sommario/riassunto | This textbook presents theory and practice in the context of automatic control education. It presents the relevant theory in the first eight chapters, applying them later on to the control of several real plants. Each plant is studied following a uniform procedure: a) the plant's function is described, b) a mathematical model is obtained, c) plant construction is explained in such a way that the reader can build his or her own plant to conduct experiments, d) experiments are conducted to determine the plant's parameters, e) a controller is designed using the theory discussed in the first eight chapters, f) practical controller implementation is performed in such a way that the reader can build the controller in practice, and g) the experimental results are presented. Moreover, the book provides a wealth of exercises and appendices reviewing the foundations of several concepts and techniques in automatic control. The control system construction proposed is based on inexpensive, easy-to-use hardware. An explicit procedure for obtaining formulas for the oscillation condition and the oscillation frequency of electronic oscillator circuits is demonstrated as well. |