

|                         |   |
|-------------------------|---|
| 1. Record Nr.           | UNINA9910484148903321   |
| Titolo                  | Biomimetic neural learning for intelligent robots : intelligent systems, cognitive robotics, and neuroscience / / Stefan Wermter, Gunther Palm, Mark Elshaw (eds.)    |
| Pubbl/distr/stampa      | Berlin ; ; New York, : Springer, c2005  |
| Edizione                | [1st ed. 2005.]   |
| Descrizione fisica      | 1 online resource (IX, 383 p.)  |
| Collana                 | Lecture notes in computer science Lecture notes in artificial intelligence, , 0302-9743 ; ; 3575<br>State-of-the-art survey   |
| Altri autori (Persone)  | WermterStefan<br>PalmGunther<br>ElshawMark  |
| Disciplina              | 629.8/92632   |
| Soggetti                | Robots - Control systems<br>Neural networks (Computer science)<br>Machine learning<br>Artificial intelligence<br>Soft computing<br>Robotics<br>Cognitive neuroscience |
| Lingua di pubblicazione | Inglese   |
| Formato                 | Materiale a stampa  |
| Livello bibliografico   | Monografia  |
| Note generali           | Proceedings of the International AI-Workshop on NeuroBotics held in 2004.   |
| Nota di bibliografia    | Includes bibliographical references and index.  |
| Nota di contenuto       | pt. 1. Biomimetic multimodal learning in neuron-based robots -- pt. 2. Biomimetic cognitive behaviour in robots.  |