

1. Record Nr.	UNISA996385668403316
Autore	Smith William <d. 1673.>
Titolo	Innocency and conscientiousness of the Quakers asserted and cleared from the evil surmises, false aspersions, and unrighteous suggestions of Judge Keeling [[electronic resource]] : expressed in his speech made the seventh of the seventh month at the sessions-house in the Old-Baily ... : wherein also is shewed that this law doth not concern them, they being no seditious sectaries, nor contrivers of insurrections, nor evil-doers, therefore no just law is against them
Pubbl/distr/stampa	Printed at London, : Published by a lover of truth and righteousness, W. S., 1664
Descrizione fisica	16, [1] p
Soggetti	Society of Friends - Great Britain Law and ethics
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Reproduction of original in Duke University Library. Attributed to William Smith. cf. BM.
Sommario/riassunto	eebo-0040

2. Record Nr.	UNINA9910484000503321
Titolo	Advances in Physical Agents : Proceedings of the 19th International Workshop of Physical Agents (WAF 2018), November 22-23, 2018, Madrid, Spain // edited by Raquel Fuentetaja Pizán, Ángel García Olaya, Maria Paz Sesmero Lorente, Jose Antonio Iglesias Martínez, Agapito Ledezma Espino
Pubbl/distr/stampa	Cham : , : Springer International Publishing : , : Imprint : Springer, , 2019
ISBN	3-319-99885-4
Edizione	[1st ed. 2019.]
Descrizione fisica	1 online resource (xi, 334 pages)
Collana	Advances in Intelligent Systems and Computing, , 2194-5365 ; ; 855
Disciplina	615.82
Soggetti	Computational intelligence Automatic control Robotics Automation Computer vision Artificial intelligence Computational Intelligence Control, Robotics, Automation Computer Vision Artificial Intelligence
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Semantic localization of a robot in a real home -- Kalman Filter -- Self-Driving a Car in simulation through a CNN -- Study of obstacle avoidance strategies for ecient autonomous.-Adaptation of the Diculty Level in an Infant-Robot Movement Contingency Study -- Change Detection Tool based on GSV to help DNNs training -- Opponent Modeling in RoboCup Soccer Simulation. First Steps Towards a General Algorithm to Estimate the Mechanical State of a Vehicle.
Sommario/riassunto	The book reports on cutting-edge theories and methods aimed at the control and coordination of agents acting and moving in a dynamic environment. It covers a wide range of systems, including multiagent

systems, domotic agents, robotic manipulators, soccer robots, autonomous and semiautonomous robots, as well as systems for industrial applications. Advances in software agents, sensors, computer visions and other related areas are also thoroughly discussed and presented in detail. Based on the 19th edition of the International Workshop of Physical Agents (WAF 2018), held on November 22-23, 2018, in Madrid, Spain, this book offers a snapshot of the state-of-the-art in the field of physical agents, with a special emphasis on autonomous systems such as mobile robots, industrial process or other complex systems. .
