1. Record Nr. UNISA996396409203316

Autore	T. D
Titolo	This for the Parliament, Counsel, and the officers of the army of the Common-wealth of England, Scotland and Ireland; in patience to read and consider, Eccle. 7. 8, 9. Hag. 1. 5. Being that the servants of the Lord are to finish their true and faithful testimony against the world, as the Lord shall move them so to do, who live and move in him, that so they may finish their course with joy; and now for this end and purpose have I given forth this my testimony, that I might be found doing the will of God, whom I serve in the Spirit of his Son, not knowing but that my service herein may be acceptable to all, or some of you, and if but to one, shall be glad, and if to none, my labour shall not be in vain in the Lord, who is the reward of all them that obey him and diligently seek him. Written about the middle of the sixth month, 1659. By a lover of the truth, as it is in Jesus, a late member of the army, known by the name of Thomas Davenport [[electronic resource]]
Pubbl/distr/stampa	London, : printed for Thomas Simmons, at the Bulla and Mouth near Aldersgate, 1659
Descrizione fisica	8 p
Soggetti	Society of Friends - Doctrines Great Britain History Commonwealth and Protectorate, 1649-1660 Early works to 1800
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Reproduction of the original in the Friends House Library, London, England.
Sommario/riassunto	eebo-0080

2. Record Nr. UNINA9910375859203321

Titolo	ACM SIGGRAPH 2017 posters / / sponsor, ACM SIGGRAPH
Pubbl/distr/stampa	New York : , : ACM, , 2017
Descrizione fisica	1 online resource (173 pages)
Disciplina	006.6
Soggetti	Computer graphics Human-computer interaction
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia

3. Record Nr. UNINA9910483031403321

Titolo	Human-Friendly Robotics 2020 : 13th International Workshop / / edited by Matteo Saveriano, Erwan Renaudo, Antonio Rodríguez-Sánchez, Justus Piater
Pubbl/distr/stampa	Cham : , : Springer International Publishing : , : Imprint : Springer, , 2021
ISBN	3-030-71356-3
Edizione	[1st ed. 2021.]
Descrizione fisica	1 online resource (x, 144 pages) : illustrations
Collana	Springer Proceedings in Advanced Robotics, , 2511-1264 ; ; 18
Disciplina	629.8 629.8924019
Soggetti	Control engineering Robotics Automation Computational intelligence Control, Robotics, Automation Computational Intelligence
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia

Nota di contenuto	Reproducible Pruning System on Dynamic Natural Plants for Field Agricultural Robots -- Robotic Muscular Assistance-As-Needed for Physical and Training/Rehabilitation Tasks: Design and Experimental Validation of a Closed-Loop Myoelectric Control in Grounded and Wearable Applications -- The i-Walk Assistive Robot: A multimodal intelligent robotic rollator providing cognitive and mobility assistance to the elderly and motor-impaired -- Toward a Cognitive Control Framework for Explainable Robotics -- Balancing Exploration and Exploitation : A Neurally Inspired Mechanism to Learn Sensorimotor Contingencies -- A Dynamic Architecture for Task Assignment and Scheduling for Collaborative Robotic Cells.
Sommario/riassunto	This book presents recent methodological, technological, and experimental developments concerning human-friendly robots and their introduction into everyday life. The book contains a selection of 10 papers presented at the 13th edition of the International Workshop on Human-Friendly Robotics (HFR). The International Workshop on Human-Friendly Robotics (HFR) is an annual meeting that brings together academic scientists, researchers, and research scholars to present their latest, original findings on all aspects concerning human-friendly robotics where safe and dependable machines operate in close proximity to humans or directly interact with them in a wide range of contexts. The 13th edition was organized by the University of Innsbruck and took place in Innsbruck, Austria. The book is primarily intended for robotics researchers and postgraduates which are doing or willing to do research in fields related to human-friendly robotics, including human–robot interaction, robot control, robot learning, and intuitive interfaces. . .