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| Autore | Anon |
| Titolo | Minne-liederen en mengelzangen. By A. Pels [[electronic resource]] |
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| Autore | Ferrando Angelo |
| Titolo | Agents and Robots for Reliable Engineered Autonomy : 4th Workshop, AREA 2024, Santiago de Compostela, Spain, October 19, 2024, Proceedings |
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| Altri autori (Persone) | CardosoRafael C |
| Soggetti | Autonomous robots
Multiagent systems |
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| Nota di contenuto | Preface -- Invited Talks -- Organisation -- Contents -- Risk-Aware On-the-Fly Solving of Physical Vehicle Routing Problems -- 1
Introduction -- 2 Related Work -- 3 Towards a Problem Formulation |

-- 4 Complexity Considerations -- 5 Implementation Considerations
-- 6 Experiments -- 7 Conclusion -- References -- Agents as a
Design Paradigm for Robotic Systems Leveraging ROS and Gazebo --
1 Introduction -- 2 Related Work -- 3 Design Concepts and the
Agent Paradigm -- 4 Developing Robotic Systems with ROS and
Gazebo -- 5 Agents for ROS and Gazebo Designing -- 5.1 Case
Study and Validation -- 6 Conclusions -- References -- Verification-
Oriented Specification of Multi-agent Interaction Patterns -- 1
Introduction -- 2 Related Work -- 3 Background -- 4 Illustrative
Example -- 5 Translating LlrAs patterns to SHA -- 5.1 Hierarchical
LlrAs Pattern Structure -- 5.2 DFA Representation

Sommario/riassunto

This book is a collection of proceedings from the 4th Workshop on Agents and Robots for Reliable Engineered Autonomy (AREA 2024), held in Santiago de Compostela, Spain. It focuses on the intersection of autonomous agents, robotics, and software engineering, highlighting the challenges and solutions in developing reliable autonomous systems. Topics include agent-based modular architectures, software engineering for robotic development, and formal verification of multi-agent systems. The workshop aims to enhance understanding and showcase applications in engineering intelligent agents and multi-agent systems, with discussions led by experts in strategic reasoning and automated planning.
