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3.2 Two-Position Double-Rocker Design3.3 Synthesis of Crank-Rocker Linkages for Specified Rocker Amplitude; 3.4 Motion Generation; 3.5 Path Synthesis; References; Problems; Chapter 4: Graphical Position, Velocity, and Acceleration Analysis for Mechanisms with Revolute Joints or Fixed Slides; 4.1 Introduction; 4.2 Graphical Position Analysis; 4.3 Planar Velocity Polygons; 4.4 Graphical Acceleration Analysis; 4.5 Graphical Analysis of a Four-Bar Mechanism; 4.6 Graphical Analysis of a Slider-Crank Mechanism; 4.7 Velocity Image Theorem; 4.8 Acceleration Image Theorem
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Chapter 7: Computational Analysis of Linkages