1. Record Nr. UNINA9910460974303321

Autore	Wiarda Howard J
Titolo	Civil Society [[electronic resource]] : The American Model And Third World Development
Pubbl/distr/stampa	New York, : Westview Press, 2003
ISBN	1-283-26148-0 9786613261489 0-8133-4620-7
Descrizione fisica	1 online resource (183 p.)
Disciplina	303.483
Soggetti	Economic development -- Political aspects Information technology -- Political aspects -- Developing countries Technology and state -- Developing countries Electronic books.
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di contenuto	CONTENTS; Preface; PART I: INTRODUCTION; 1 Civil Society, Democracy, and Corporatism in the Third World; PART II: THEORY AND CONCEPTS; 2 Civil Society: History and Meaning(s); 3 Corporatist Systems of Civil Society; PART III: CASE STUDIES IN CIVIL SOCIETY; 4 Sub-Saharan Africa; 5 East Asia; 6 Latin America; 7 The Middle East and Islamic Society; 8 Is Civil Society Exportable?: The American Modeland Third World Development; Suggested Readings; About the Author; Index
Sommario/riassunto	Considers the possibility of opening up economies and societies of the Third World to democracy; specifically the role of civil society in contributing to democracy and the varieties of civil society and state-society relations in distinct Third World areas.

2. Record Nr. UNINA9910483694403321

Autore	MahmoudZadeh Somaiyeh
Titolo	Autonomy and Unmanned Vehicles : Augmented Reactive Mission and Motion Planning Architecture / / by Somaiyeh MahmoudZadeh, David M.W. Powers, Reza Bairam Zadeh
Pubbl/distr/stampa	Singapore : , : Springer Singapore : , : Imprint : Springer, , 2019
ISBN	981-13-2245-7
Descrizione fisica	1 online resource (116 pages)
Collana	Cognitive Science and Technology, , 2195-3988
Disciplina	623.74
Soggetti	Engineering Mathematical optimization Artificial intelligence Operations research Computer vision Computational Intelligence Optimization Artificial Intelligence Operations Research/Decision Theory Control, Robotics, Mechatronics Computer Imaging, Vision, Pattern Recognition and Graphics
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Nota di contenuto	Introduction to Autonomy and Applications -- State-of-the-art in UVs' Autonomous Mission Planning and Task Managing Approach -- State-of-the-art in UVs' Autonomous Motion Planning -- Advancing Autonomy by Developing a Mission Planning Architecture -- Mission Planning in Terms of Task-Time Management and Routing -- AUV Online Real-Time Motion Planning -- Augmented Reactive Mission Planning Architecture.
Sommario/riassunto	This book addresses higher–lower level decision autonomy for autonomous vehicles, and discusses the addition of a novel architecture to cover both levels. The proposed framework's performance and stability are subsequently investigated by employing

different meta-heuristic algorithms. The performance of the proposed architecture is shown to be largely independent of the algorithms employed; the use of diverse algorithms (subjected to the real-time performance of the algorithm) does not negatively affect the system's real-time performance. By analyzing the simulation results, the book demonstrates that the proposed model provides perfect mission timing and task management, while also guaranteeing secure deployment. Although mainly intended as a research work, the book's review chapters and the new approaches developed here are also suitable for use in courses for advanced undergraduate or graduate students.