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Nota di contenuto	Gaze in Human-Robot Communication; Editorial page; Title page; LCC data; Table of contents; Introduction to the Special Issue on Gaze in human-robot communication; 1. Introduction; 1.1 Gaze in human communication; 1.2 Gaze in human-agent interaction; 1.3 Gaze and human-robot communication; 2. The Special Issue; References; Design of a gaze behavior at a small mistake moment for a robot; 1. Introduction; 2. Data collection; 3. Experiments; 3.1 Hypotheses and predictions about apologies; 3.2 Hypotheses and prediction for friendliness and dissatisfaction 3.2.1 Hypothesis that assumes advantages of looking down3.2.2 Hypothesis that assumes advantages of looking at the other; 3.3 Participants; 3.4 Tasks; 3.5 Robot; 3.6 Conditions; 3.7 Procedure; 3.8 Measurement; 4. Results; 4.1 Verification of prediction 1; 4.2 Verification of prediction 2; 4.3 Verification of prediction 3; 5. Discussion; 5.1 Analysis of free descriptions; 5.2 Responsiveness to mistakes; 6. Conclusion; Acknowledgements; References; Robots can be perceived as goal-oriented agents; 1. Introduction; 2. Methods; 2.1

Subjects; 2.2 Action demonstrators; 2.2.1 The human demonstrator
 2.3 The humanoid robot; 2.4 Experimental paradigm; 2.5 Data Analysis;
 3. Results; 4. Discussion; Acknowledgments; References; Can infants
 use robot gaze for object learning?; 1. Introduction; 2. Experiment 1;
 2.1 Method; 2.1.1 Participants; 2.1.2 Apparatus; 2.1.3 Stimuli and
 procedure; 2.1.4 Data analysis; 2.2 Results and discussion; 3.
 Experiment 2; 3.1 Method; 3.1.1 Participants; 3.1.2 Stimuli and
 procedure; 3.1.3 Results and discussion; 4. General Discussion;
 Acknowledgements; References; Interactions between a quiz robot and
 multiple participants; 1. Introduction
 2. Background of this study; 2.1 Cross-cultural communicative
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 actions and questioning strategy; 3. The present experiment: A quiz
 robot in Japanese and English; 3.1 Robot System; 3.2 Experimental
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 5.1 Comparing responses during the keyword (in Q3); 5.2 Comparing
 responses to tag-part of a tag-question (in Q6); 6. Discussion and
 Conclusion; Acknowledgement; References; Cooperative gazing
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 2. A human multi-robot multimodal interactive paradigm; 2.1 Gaze-
 Contingent platform; 2.2 Experiment design; 2.3 Hypotheses; 2.4
 Experimental procedure; 2.5 Data collection; 2.6 Validation of the
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 3.2 Speech acts; 3.3 Attention dynamics around naming moments; 4.
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 4.2 Micro-level mutual reflexivity; 5. Conclusion; Acknowledgements;
 References; Learning where to look Autonomous development of Gaze
 behavior for natural Human-Robot Interaction; 1. Introduction
 2. Reactive Gaze Controller
