

1. Record Nr.	UNINA9910459108003321
Autore	Benson Ophelia
Titolo	Does God hate women? // Ophelia Benson and Jeremy Stangroom
Pubbl/distr/stampa	London, [England] ; ; New York, New York : , : Continuum, , 2009 ©2009
ISBN	1-282-87334-2 9786612873348 1-4411-1862-4
Descrizione fisica	1 online resource (213 p.)
Disciplina	200.82
Soggetti	Women and religion Electronic books.
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Includes index.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	A God of bullies -- Religious apologetics, Islam, and caricature -- The world and the kitchen -- Honour is between the legs of women -- Holy groupthink -- Mutilate in the name of purity -- Islam, Islamophobia, and risk -- Lipstick on a pig.
Sommario/riassunto	www.doesgodhatewomen.com. This fascinating book explores the role that religion and culture play in the oppression of women. Benson and Stangroom ask probing questions about the way that religion shields the oppression of women from criticism and why many Western liberals, leftists and feminists have remained largely silent on the subject. Throughout the world, a great many women lead lives of misery and sometimes plain horror. They are often considered and treated as the property of men and have few, if any, rights. Such treatment is generally sustained and protected by a combination of reli

2. Record Nr.	UNINA9910483847603321
Autore	Kurzhanski Alexander B
Titolo	Dynamic Programming for Impulse Feedback and Fast Controls : The Linear Systems Case // by Alexander B. Kurzhanski, Alexander N. Daryin
Pubbl/distr/stampa	London : , : Springer London : , : Imprint : Springer, , 2020
ISBN	1-4471-7437-2
Edizione	[1st ed. 2020.]
Descrizione fisica	1 online resource (XIII, 275 p. 26 illus., 1 illus. in color.)
Collana	Lecture Notes in Control and Information Sciences, , 1610-7411 ; ; 468
Disciplina	519.703
Soggetti	Control engineering System theory Control theory Control and Systems Theory Systems Theory, Control
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Includes index.
Nota di contenuto	Introduction: Why Impulses? -- Part I: Ordinary Impulses -- Open-Loop Impulse Control -- Closed-Loop Impulse Control -- Impulse Control under Uncertainty -- State-Constrained Impulse Control -- State Estimation Under Ordinary Impulsive Inputs -- Part II: Impulses of Higher Order. Realizability and Fast Control -- The Open-Loop and Closed-Loop Impulse Controls -- State-Constrained Control under Higher Impulses -- State Estimation and State-Constrained Control -- Generalized Duality Theory: The Increasing and Decreasing Lagrangian Scales -- Realistic Controls -- Closed-Loop Fast Controls -- Appendix: Uniqueness of Viscosity Solutions.
Sommario/riassunto	Dynamic Programming for Impulse Feedback and Fast Controls offers a description of feedback control in the class of impulsive inputs. This book deals with the problem of closed-loop impulse control based on generalization of dynamic programming techniques in the form of variational inequalities of the Hamilton–Jacobi–Bellman type. It provides exercises and examples in relation to software, such as techniques for regularization of ill-posed problems. It also gives an introduction to applications such as hybrid dynamics, control in arbitrary small time,

and discontinuous trajectories. This book walks the readers through: the design and description of feedback solutions for impulse controls; the explanation of impulses of higher order that are derivatives of delta functions; the description of their physically realizable approximations - the fast controls and their approximations; the treatment of uncertainty in impulse control and the applications of impulse feedback. Of interest to both academics and graduate students in the field of control theory and applications, the book also protects users from common errors, such as inappropriate solution attempts, by indicating Hamiltonian techniques for hybrid systems with resets.
