1. Record Nr. UNINA9910456899303321

Titolo	The language and style of film criticism / / edited by Alex Clayton and Andrew Klevan
Pubbl/distr/stampa	Abingdon, Oxon : , : Routledge, , 2011
ISBN	1-136-72828-7 1-283-24171-4 9786613241719 1-136-72829-5 0-203-81731-1
Descrizione fisica	1 online resource (209 p.)
Altri autori (Persone)	ClaytonAlex KlevanAndrew
Disciplina	808/.066791
Soggetti	Film criticism Motion pictures - Philosophy Electronic books.
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	The Language and Style of Flim Criticism; Copyright; Contents; List of figures; Contributors; Introduction: the language and style of film criticism; 1 Coming to terms; 2 Questioning style; 3 Incursions; 4 Description; 5 Writing about performance: the film critic as actor; 6 Silence and stasis; 7 Four against the house; 8 Being seized; 9 Memories that don't seem mine; 10 La camera-stylo: notes on video criticism and cinephilia; Index
Sommario/riassunto	The Language and Style of Film Criticism brings together original essays from an international range of academics and film critics highlighting the achievements, complexities and potential of film criticism.In recent years, in contrast to the theoretical, historical and cultural study of film, film criticism has been relatively marginalised, especially within the academy. This book highlights the distinctiveness of film criticism and addresses ways in which it can take a more central place within the academy and develop in dynamic ways outside it. <EM

2. Record Nr. UNINA9910346957903321

Autore	Mandery Christian
Titolo	Organisation, Repräsentation und Analyse menschlicher Ganzkörperbewegung für die datengetriebene Bewegungsgenerierung bei humanoiden Robotern
Pubbl/distr/stampa	KIT Scientific Publishing, 2017
ISBN	1000075715
Descrizione fisica	1 electronic resource (VIII, 308 p. p.)
Collana	Karlsruhe Series on Humanoid Robotics
Lingua di pubblicazione	Tedesco
Formato	Materiale a stampa
Livello bibliografico	Monografia
Sommario/riassunto	This work presents an approach to data-driven motion generation for humanoid robots, which is based on the observation and analysis of human whole-body motions. To this end, we investigate how captured human motions can be represented, classified and organized in a large-scale motion database. The statistical modeling of the transitions between characteristic whole-body poses enables the subsequent generation of multi-contact motions.