

1. Record Nr.	UNINA9910455418103321
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Titolo	State observers for linear systems with uncertainty [[electronic resource] /] / by Sergey K. Korovin and Vasily V. Fomichev
Pubbl/distr/stampa	Berlin ; ; New York, : Walter De Gruyter, c2009
ISBN	1-282-34541-9 9786612345418 3-11-021813-5
Descrizione fisica	1 online resource (252 p.)
Collana	De Gruyter expositions in mathematics ; ; 51
Classificazione	ZQ 5080
Altri autori (Persone)	FomichevV. V
Disciplina	629.8/312
Soggetti	Control theory Linear systems Electronic books.
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references (p. 233-240) and index.
Nota di contenuto	Frontmatter -- Contents -- Chapter 1. Notion of state observers -- Chapter 2. Observability -- Chapter 3. Observers of full-phase vector for fully determined linear systems -- Chapter 4. Functional observers for fully determined linear systems -- Chapter 5. Asymptotic observers for linear systems with uncertainty -- Chapter 6. Observers for bilinear systems -- Chapter 7. Observers for discrete systems -- Backmatter
Sommario/riassunto	This book presents the basic concepts and recent developments of linear control problems with perturbations. The presentation concerns both continuous and discrete dynamical systems. It is self-contained and illustrated by numerous examples. From the contents: Notion of state observers Observability Observers of full-phase vectors for fully determined linear systems Functional observers for fully determined linear systems Asymptotic observers for linear systems with uncertainty Observers for bilinear and discrete systems