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Disciplina	003
Soggetti	Observers (Control theory)
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Nota di contenuto	Systems under Consideration What Is Observability? The New Observability Theory Versus the Old Ones Observability and Observers Observability Concepts Infinitesimal and Uniform Infinitesimal Observability The Canonical Flag of Distributions The Phase-Variable Representation Differential Observability and Strong Differential Observability The Trivial Foliation Appendix: Weak Controllability The Case d[subscript y] [less than or equal] d [subscript u] Relation Between Observability and Infinitesimal Observability Normal Form for a Uniform Canonical Flag Characterization of Uniform Infinitesimal Observability Complements Proof of Theorem 3.2 The Case d[subscript y]] d[subscript u] Definitions and Notations Statement of Our Differential Observability Results Proof of the Observability Theorems Equivalence between

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	Observability and Observability for Smooth Inputs The Approximation Theorem Complements Singular State-Output Mappings Assumptions and Definitions The Ascending Chain Property The Key Lemma The ACP(N) in the Controlled Case Globalization The Controllable Case Observers: The High-Gain Construction Definition of Observer Systems and Comments The High-Gain Construction Dynamic Output Stabilization and Applications Dynamic Output Stabilization and Applications Dynamic Output Stabilization The Case of a Uniform Canonical Flag The General Case of a Phase-Variable Representation Complements Applications Binary Distillation Columns Polymerization Reactors.
Sommario/riassunto	This 2001 book presents a general theory as well as a constructive methodology to solve 'observation problems', that is, reconstructing the full information about a dynamical process on the basis of partial observed data. A general methodology to control processes on the basis of the observations is also developed. Illustrative but also practical applications in the chemical and petroleum industries are shown. This book is intended for use by scientists in the areas of automatic control, mathematics, chemical engineering and physics.