

1. Record Nr.	UNINA9910454324803321
Autore	IAkubovich V. A (Vladimir Andreevich)
Titolo	Stability of stationary sets in control systems with discontinuous nonlinearities [[electronic resource] /] / V.A. Yakubovich, G.A. Leonov, A. Kh. Gelig
Pubbl/distr/stampa	River Edge, NJ, : World Scientific, c2004
ISBN	1-281-93440-2 9786611934408 981-279-423-9
Descrizione fisica	1 online resource (352 p.)
Collana	Series on stability, vibration, and control of systems. Series A ; ; v. 14
Altri autori (Persone)	LeonovG. A (Gennadii Alekseevich) GeligArkadii Khaimovich
Disciplina	629.836
Soggetti	Control theory Nonlinear control theory Set theory System analysis Differential equations, Nonlinear Engineering mathematics Engineering systems Electronic books.
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references (p. 323-332) and index.
Nota di contenuto	Contents ; Preface ; List of Notations ; 1. Foundations of Theory of Differential Equations with Discontinuous Right-Hand Sides ; 1.1 Notion of Solution to Differential Equation with Discontinuous Right-Hand Side 1.1.1 Difficulties encountered in the definition of a solution. Sliding modes 1.1.2 The concept of a solution of a system with discontinuous nonlinearities accepted in this book. Connection with the theory of differential equations with multiple-valued right-hand sides 1.1.3 Relation to some other definitions of a solution to a system with

discontinuous right-hand side

1.1.4 Sliding modes. Extended nonlinearity. Example

; 1.2 Systems of Differential Equations with Multiple-Valued Right-Hand Sides (Differential Inclusions)

1.2.1 Concept of a solution of a system of differential equations with a multivalued right-hand side the local existence theorem the theorems on continuation of solutions and continuous dependence on initial values

1.2.2 "Extended" nonlinearities
modes

; 1.2.3 Sliding

1.3 Dichotomy and Stability

1.3.1 Basic definitions

; 1.3.2 Lyapunov-type lemmas

; 2. Auxiliary

Algebraic Statements on Solutions of Matrix Inequalities of a Special Type

2.1 Algebraic Problems that Occur when Finding Conditions for the Existence of Lyapunov Functions from Some Multiparameter Functional Class. Circle Criterion. Popov Criterion

Sommario/riassunto

This book presents a development of the frequency-domain approach to the stability study of stationary sets of systems with discontinuous nonlinearities. The treatment is based on the theory of differential inclusions and the second Lyapunov method. Various versions of the Kalman-Yakubovich lemma on solvability of matrix inequalities are presented and discussed in detail. It is shown how the tools developed can be applied to stability investigations of relay control systems, gyroscopic systems, mechanical systems with a Coulomb friction, nonlinear electrical circuits, cellular neural networks
