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Sommario/riassunto	Robotics: Science and Systems III spans a wide spectrum of robotics, bringing together researchers working on the foundations of robotics, robotics applications, and analysis of robotics systems. This volume presents the proceedings of the third annual Robotics: Science and Systems conference, held in June 2007 at Georgia Tech. Papers report state-of-the-art research on topics as diverse as Legged Robotics, Reconfigurable Robots, Biomimetic Robots, Manipulation, Humanoid Robotics, Telerobotics, Haptics, Motion Planning, Collision Avoidance, Robot Vision and Perception, Bayesian Techniques, Machine Learning, Mobile Robots, and Multi-robot systems. This conference reflects not only the tremendous growth of robotics as a discipline but also the desire in the robotics community for a flagship event at which the best of the research in the field can be presented. Wolfram Burgard is

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