1. Record Nr. UNINA9910449689803321 Autore Karris Steven T Titolo Introduction to Simulink with engineering applications [[electronic resource] /] / Steven T. Karris Fremont, CA,: Orchard Publications, c2006 Pubbl/distr/stampa **ISBN** 1-280-43708-1 9786610437085 0-9744239-8-X Descrizione fisica 1 online resource (577 p.) Disciplina 620,002 Soggetti Computer simulation Electronic books. Lingua di pubblicazione Inglese **Formato** Materiale a stampa Monografia Livello bibliografico Note generali Description based upon print version of record. Nota di bibliografia Includes bibliographical references and index. ""Table of Contents"": ""Chapter 1"": ""1.1 Simulink and its Relation to Nota di contenuto MATLAB""; ""1.2 Simulink Demos""; ""1.3 Summary""; ""1.4 Exercises""; ""1.5 Solutions to End-of-Chapter Exercises""; ""Chapter 2""; ""2.1 The Inport, Outport, and Subsystem Blocks""; ""2.2 The Ground Block""; ""2.3 The Terminator Block""; ""2.4 The Constant and Product Blocks""; ""2.5 The Scope Block""; ""2.6 The Bus Creator and Bus Selector Blocks""; ""2.7 The Mux and Demux Blocks""; ""2.8 The Switch Block""; ""2.9 The Sum Block""; ""2.10 The Gain Block""; ""2.11 The Relational Operator Block"" ""2.12 The Logical Operator Block"""2.13 The Saturation Block""; ""2.14 The Integrator Block""; ""2.15 The Unit Delay Block""; ""2.16 The Discrete-Time Integrator Block""; ""2.17 Data Types and The Data Type Conversion Block""; ""2.18 Summary""; ""2.19 Exercises""; ""2.20 Solutions to End-of-Chapter Exercises""; ""Chapter 3""; ""3.1 The Continuous-Time Linear Systems Sub-Library""; ""3.1.3 The State-Space Block""; ""3.1.4 The Transfer Fcn Block""; ""3.1.5 The Zero-Pole Block""; ""3.2 The Continuous-Time Delays Sub-Library""; ""3.2.1 The Transport Delay Block"" ""3.2.2 The Variable Time Delay Block"""3.2.3 The Variable Transport

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## Sommario/riassunto

This text is an introduction to Simulink, a companion application to MATLAB. It is written for students at the undergraduate and graduate programs, as well as for the working professional. Although some previous knowledge of MATLAB would be helpful, it is not absolutely necessary; Appendix A of this text is an Introduction to MATLAB to enable the reader to begin learning both MATLAB and Simulink to perform graphical computations and programming. Chapters 2 through 18 describe the blocks of all Simulink libraries. Their application is illustrated with practical examples through Simulink models,