Record Nr.	UNINA9910438056503321
Autore	Kharitonov Vladimir L
Titolo	Time-delay systems : Lyapunov functionals and matrices / / Vladimir L. Kharitonov
Pubbl/distr/stampa	[New York], : Birkhauser, c2013
ISBN	1-283-62170-3 9786613934154 0-8176-8367-4
Edizione	[1st ed. 2013.]
Descrizione fisica	1 online resource (323 p.)
Collana	Control engineering
Disciplina	629.8 629.83
	Lyapunov functions Matrices
Lingua di pubblicazione	Inglese
Formato	Materiale a stampa
Livello bibliografico	Monografia
Note generali	Description based upon print version of record.
Nota di bibliografia	Includes bibliographical references and index.
Nota di contenuto	pt. 1. Retarded type systems pt. 2. Neutral type systems.
Sommario/riassunto	Stability is one of the most studied issues in the theory of time-delay systems, but the corresponding chapters of published volumes on time-delay systems do not include a comprehensive study of a counterpart of classical Lyapunov theory for linear delay free systems. The principal goal of the book is to fill this gap, and to provide readers with a systematic and exhaustive treatment of the basic concepts of the Lyapunov-Krasovskii approach to the stability analysis of linear time-delay systems. The book is organized into two parts. The first part is dedicated to the case of retarded type time-delay systems; it consists of four chapters, which respectively deal with results concerning the existence and uniqueness of the solutions of an initial value problem, the class of linear systems with one delay, the case of systems with several delays, and the case of systems with distributed delays. The second part of the book studies the case of neutral type time-delay systems delay systems, containing three chapters that extend the results presented earlier in the book to neutral time-delay systems and treating special classes of linear time-delay systems. Time-Delay Systems: Lyapunov

1.

Functionals and Matrices will be of great use and interest to researchers
and graduate students in automatic control and applied mathematics as
well as practicing engineers involved in control system design.